

SERC Doctoral Students Research Forum · 2026

From Correlation to Intervention: Causal Root-Cause Diagnosis in Nonstationary Industrial Time Series

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Industrial Fault Diagnosis: A Harder Problem to Solve

The Predictive Maintenance Chain

DETECT

Is something wrong?

DIAGNOSE

What is the root cause?

GAP

PROGNOSE

How long until failure?

DECIDE

What action to take?

Why Root Cause Diagnosis Often Remains Unsolved



Correlation \neq Causation

Downstream symptoms look like root causes in the data



Non-stationarity

Machine behavior shifts across operating regimes



Observational data only

No controlled experiments in safety-critical plants



Overclaiming is common

Models force answers even when evidence is too weak

The Root Cause Gap: Correlation Is Not Enough for Action

Level 1

What?

Association

Variables move together

xmv(3) correlates with quality drop

**Most PdM
stops here.**

Level 2

What if?

Intervention

What if I change X?

If I set xmv(3)=52, does quality recover?

SCOPE OF THIS RESEARCH

Level 3

Why?

Counterfactual

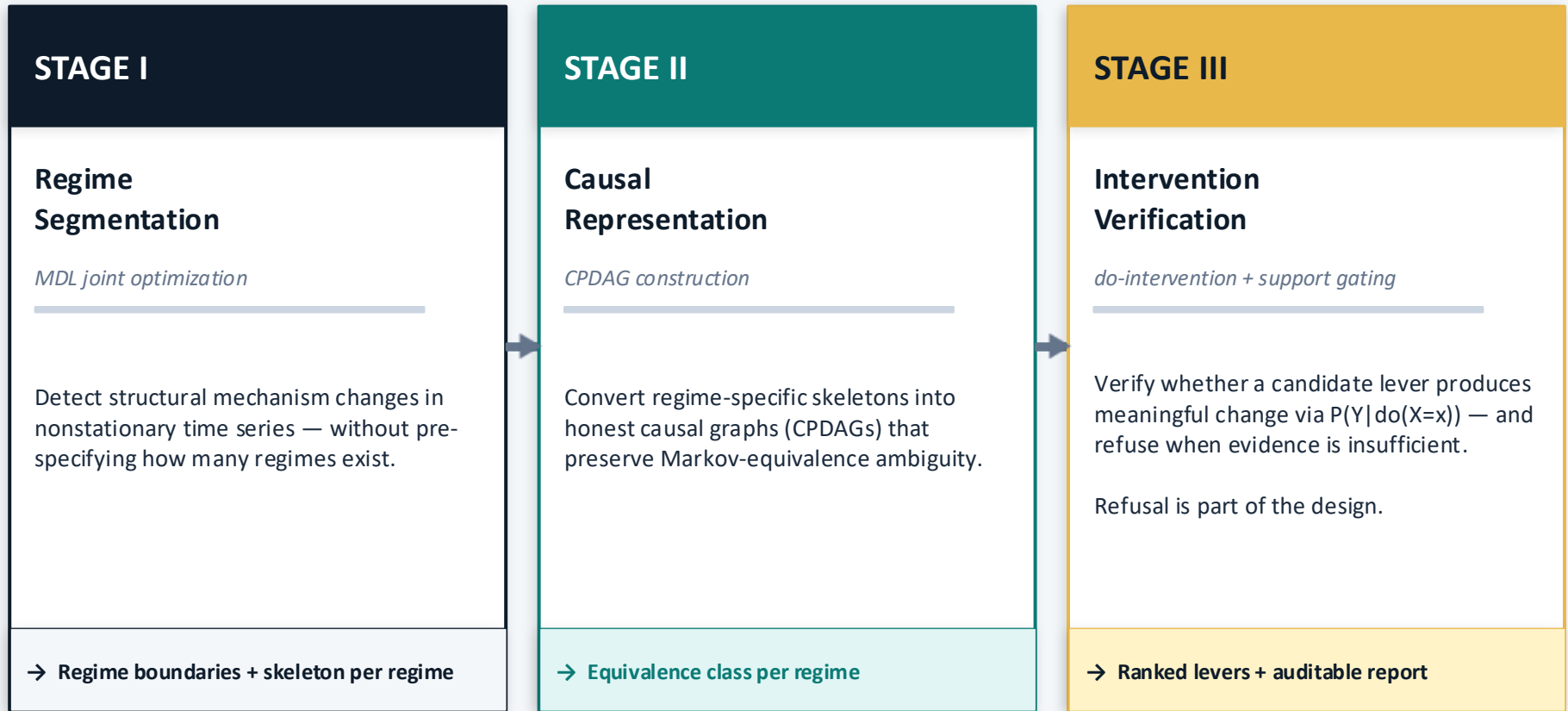
Why did this happen?

Would failure have occurred without this fault?

**Most sophisticated level
(We are not there yet).**

The core challenge: derive intervention-level root-cause answers from purely observational, nonstationary industrial data — without experiments.

Artifact: Three-Stage Causal Diagnostic Protocol



STAGE I

Regime Segmentation & Skeleton Discovery

The Challenge

Segmentation and structure learning depend on each other — a chicken-and-egg problem. You cannot learn regime boundaries without knowing the causal structure, and vice versa.

The MDL Solution

Solve both simultaneously via Minimum Description Length (MDL) optimization. A new regime is admitted only when added complexity is justified by improved data compression.

- ✓ Nonparametric (Gaussian Processes) — no restrictive parametric assumptions
- ✓ Greedy search + random restarts — scalable to industrial datasets
- ✓ Each regime gets its own causal skeleton — not a blended global model

Output → Regime boundaries + regime-specific causal skeleton

STAGE II

Causal Representation – CPDAG Construction

What is a CPDAG?

A Completed Partially Directed Acyclic Graph (CPDAG) represents the full Markov equivalence class supported by the data:



Directed edge: where evidence is compelled



Undirected edge: where ambiguity remains

Key design choice: preserve uncertainty — don't force one DAG when the data don't justify it.

Statistical Tools

- HSIC-based independence testing — nonlinear dependence
- KCIT — identifies collider structures
- Cross-fitted residual tests — directional asymmetry
- Block bootstrap calibration — accounts for serial dependence
- Benjamini–Yekutieli FDR control — multiple testing
- Meek rules — propagate admissible orientations

Output → One CPDAG per regime — honest, ambiguity-preserving causal representation

STAGE III

Interventional Root-Cause Verification

Root cause definition: A variable is a root cause if a feasible intervention on it — $P(Y | do(X = x))$ — produces a meaningful outcome change.

① Abduction

Fit the regime-specific model to the observed sensor history.

② Action

Replace the structural equation of the candidate variable with an assigned feasible value.

③ Prediction

Propagate the modified model forward to compute the downstream outcome distribution.

Guardrails: Support gating flags extrapolations. Structural averaging across all CPDAG-consistent DAGs propagates uncertainty.

Refuses when the evidence is insufficient.

Three validity conditions must hold: causal ancestry, identifiability, and empirical support.

Output → Ranked actionable levers + uncertainty bounds + 'refuse' flags + auditable evidence trail

Fault 6 — A-Feed Loss: Protocol Confirms Root Cause

STAGE I — 3 Regimes Detected

R1 Pre-fault t = 0–180	Mean 4.20 Std 0.56
R2 Onset t = 180–360	Mean 3.45 Std 0.05
R3 Fault steady t=360–500	Mean 3.46 Std 0.06

Sharp change at t=180

Sharp shift at t=180: mean drops 0.75, variance collapses 10x

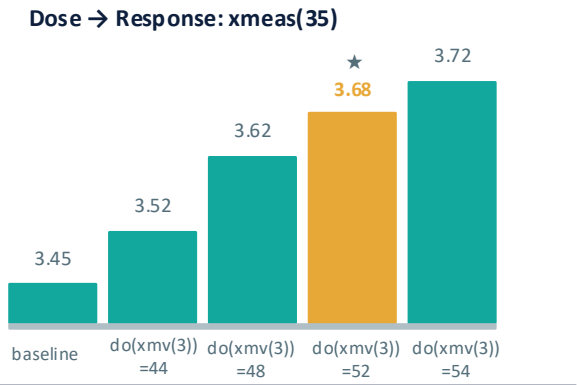
STAGE II — Causal Structure

xmv(3)
 ✓ Admissible upstream actuator
 Directed ancestor of xmeas(35)
 across ALL valid DAG extensions

Other xmv(k)
 ✗ Excluded
 No directed path to xmeas(35) in any valid DAG

xmeas(·) vars
 ✗ Downstream only
 Correctly labeled as symptoms, not root cause candidates

STAGE III — Intervention Result



+6.7% improvement · 95% CI excludes zero

Fault 6 is a direct actuator fault. One valve fails. The signal is clear. The protocol found the root cause.

VERDICT: ✓ Root cause identified and verified — xmv(3) is the confirmed actionable lever.

Fault 1 — A/C-Feed Ratio: Protocol Refuses to Overclaim

STAGE I — Regimes Detected

3 regimes found

t = 0–180, 180–360, 360–500

Shifts are subtle

Statistically weaker than Fault 6

Boundaries less sharp

Mechanism change is ambiguous

*No sharp structural break
identified at mechanism level*

STAGE II — Structural Finding

No actuator $x_{mv}(k)$

✗ No directed ancestor of $x_{meas}(35)$
in any valid DAG extension

Other $x_{mv}(k)$

✗ Also excluded — no valid path

$x_{meas}(\cdot)$ vars

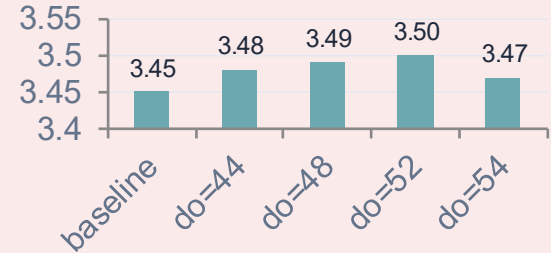
✗ Downstream only — correctly excluded

Graph structurally indeterminate for action

STAGE III — Intervention Estimate

Intervention Estimate: $x_{meas}(35)$

Only a small drift



CI crosses zero · Support gating flags insufficient evidence

✗ Diagnosis explicitly withheld

Fault 1 is a ratio and composition disturbance (subtle). No single actuator is directly responsible. The signal is not clear. The protocol found no root cause.

Refusal is not failure. Withholding a diagnosis when evidence is too weak is the scientifically honest and safety-critical correct output. **Overclaiming is the real failure.**

Scientific Maturity: Knowing When NOT to Claim a Root Cause

Fault 1 is a stress test, and the protocol's correct refusal is a scientific contribution, not a failure.

Fault 6 — Affirmative Case

Stage I	3 clear regimes — sharp mechanism shifts confirmed
Stage II	xmv(3) directed ancestor of xmeas(35) in all valid DAGs
Stage III	do(xmv(3)=52) → +6.7% improvement, CI excludes zero
Verdict	✓ Root cause identified and verified

Fault 1 — Conservative Case

Stage I	3 regimes found — but shifts are subtle, statistically weaker
Stage II	No actuator with directed path to xmeas(35) in any valid DAG
Stage III	Intervention effect: modest drift, on-support doses only, withheld
Verdict	✓ Overclaiming prevented — withheld, with explanation

Both outcomes are success conditions. The protocol addresses all identified gaps: regime awareness, uncertainty preservation, and validity-guarded diagnosis.

The Output: An Auditable, Decision-Ready Diagnostic Report

CAUSAL DIAGNOSTIC REPORT · Tennessee Eastman Process · $x_{meas}(35)$ = Product Quality

SCENARIO CONTEXT

Fault: Fault 6 (A-feed loss)

Regimes: 3 detected (R1, R2, R3)

Change pts: $t=180, t=360$

Outcome var: $x_{meas}(35)$

Nonstationarity: Confirmed

STRUCTURAL FINDING

Main lever: $x_{mv}(3)$ ✓ Admissible

Path status: Directed ancestor (all DAGs)

Regime stable?: Yes — R1, R2, R3

Competing $x_{mv}(k)$: Excluded (no path)

$x_{meas}(\cdot)$ as root?: Rejected (downstream)

INTERVENTION VERDICT

Action: $do(x_{mv}(3) = 52)$

Baseline: $x_{meas}(35) = 3.45$

Post-intervention: $x_{meas}(35) = 3.68$

Effect size: +6.7% (CI excludes 0)

Validity status: ✓ SUPPORTED

Every conclusion is traceable: regime context → structural evidence → intervention estimate → validity status. Engineers can ask 'Why was this claimed?' or 'Why was this withheld?' — and the report answers.

Contributions That Move the Field Forward

01

A new diagnostic paradigm

The first regime-aware, intervention-oriented causal diagnostic protocol for nonstationary industrial time series — unifying temporal, structural, and causal reasoning in one artifact.

02

Joint segmentation & structure learning

Breaks the circular dependency between regime boundaries and mechanism discovery by solving both simultaneously via MDL optimization.

03

Uncertainty-preserving causal representation

CPDAG output instead of a forced DAG — structural ambiguity is preserved and carried forward, not silently erased.

04

Intervention-grounded root-cause definition

A variable is a root cause only if $do(X=x)$ produces a meaningful outcome change under validity constraints — not merely because of correlation.

05

Principled refusal as a scientific output

The protocol explicitly withholds judgment when data or structure cannot support a claim — treating epistemic discipline as a design requirement, not a limitation.

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Why This Matters: Safer Diagnosis in Safety-Critical Systems

Beyond correlation



Moves predictive maintenance from pattern-matching to intervention-oriented causal reasoning — enabling engineers to act on root causes, not symptoms.

Safer claims



In complex plants, downstream symptoms can easily masquerade as root causes. Explicit guardrails protect engineers from acting on plausible-but-wrong conclusions.

Decision-ready under uncertainty



Outputs are not just predictions — they are ranked levers with uncertainty quantification, refusal flags, and auditable reasoning trails.

Reusable template



The three-stage protocol generalizes to any safety- or reliability-critical system where operating conditions change over time — aerospace, energy, manufacturing.

The Takeaway

This dissertation develops a complete, operationalizable protocol for moving from messy observational data to a causal diagnosis that is actually useful for engineering action.

Learns regime-specific causal context — no single global model forced onto shifting data

Preserves structural ambiguity honestly — CPDAGs instead of arbitrary DAGs

Verifies root causes through intervention — $P(Y | do(X=x))$, not just correlation

Enforces support and identifiability guardrails — refuses to overclaim

Delivers auditable, decision-ready outputs for maintenance engineers

Questions?

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Solution is a Protocol

3-Stage Causal Diagnostic

Method

MDL + CPDAG + intervention

Benchmark

Tennessee Eastman Process

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