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# **Advancing Systems Engineering through a Mathematically-Rigorous Co-Pilot**

Paul Wach, PhD, Research Assistant Professor  
18 Sep 2025

SERC Workshop on AI4SE



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# Some Upfront Thank You(s)!



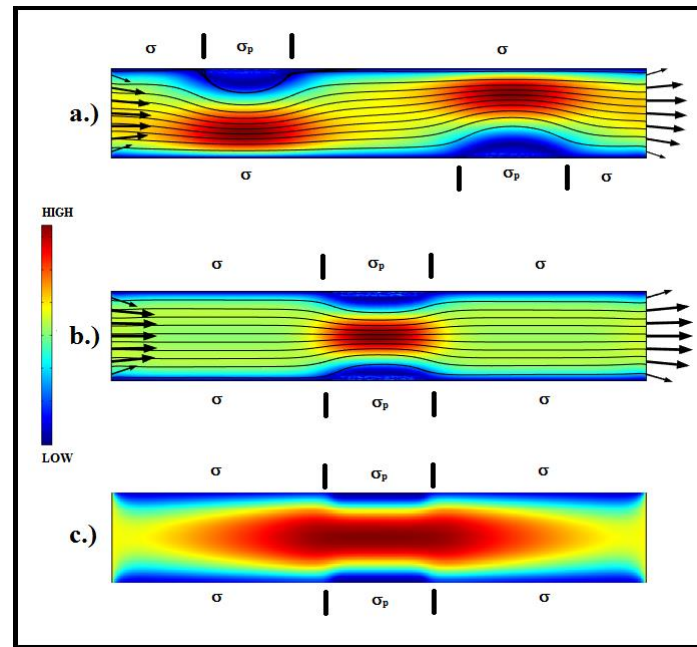
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- The work has been realized thanks to several contributors and sponsors
- Collaborators include:
  - Bernie Zeigler, DH Kim, and RTSync associates
    - Content shared with permission
  - Brad Philipbar, Senior Wargaming Fellow, Institute for Future Conflict (IFC), USAFA
    - Content shared with permission
  - Peter Beling, Adi Iyer, Grant Anderson, Mary Nerayo, Cameron Curran, Bhavya Shanmugum

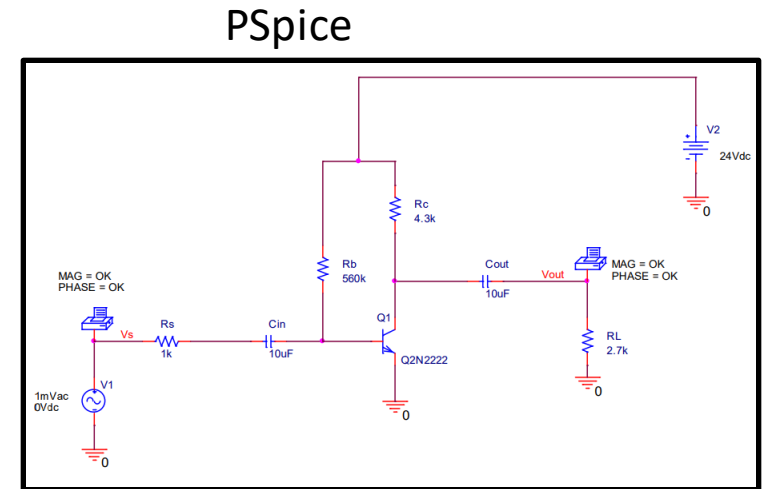


# How does Systems Engineering Maturity Compare to Other Engineering Domains?

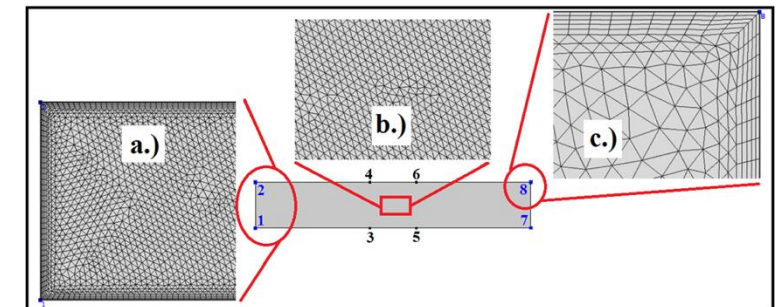
- Engineering domains (other than Systems Engineering) have theoretical foundations upon which software platforms are implemented
- Reinvigorated calls for theoretical foundations of SE



^ Computational fluid dynamics ^



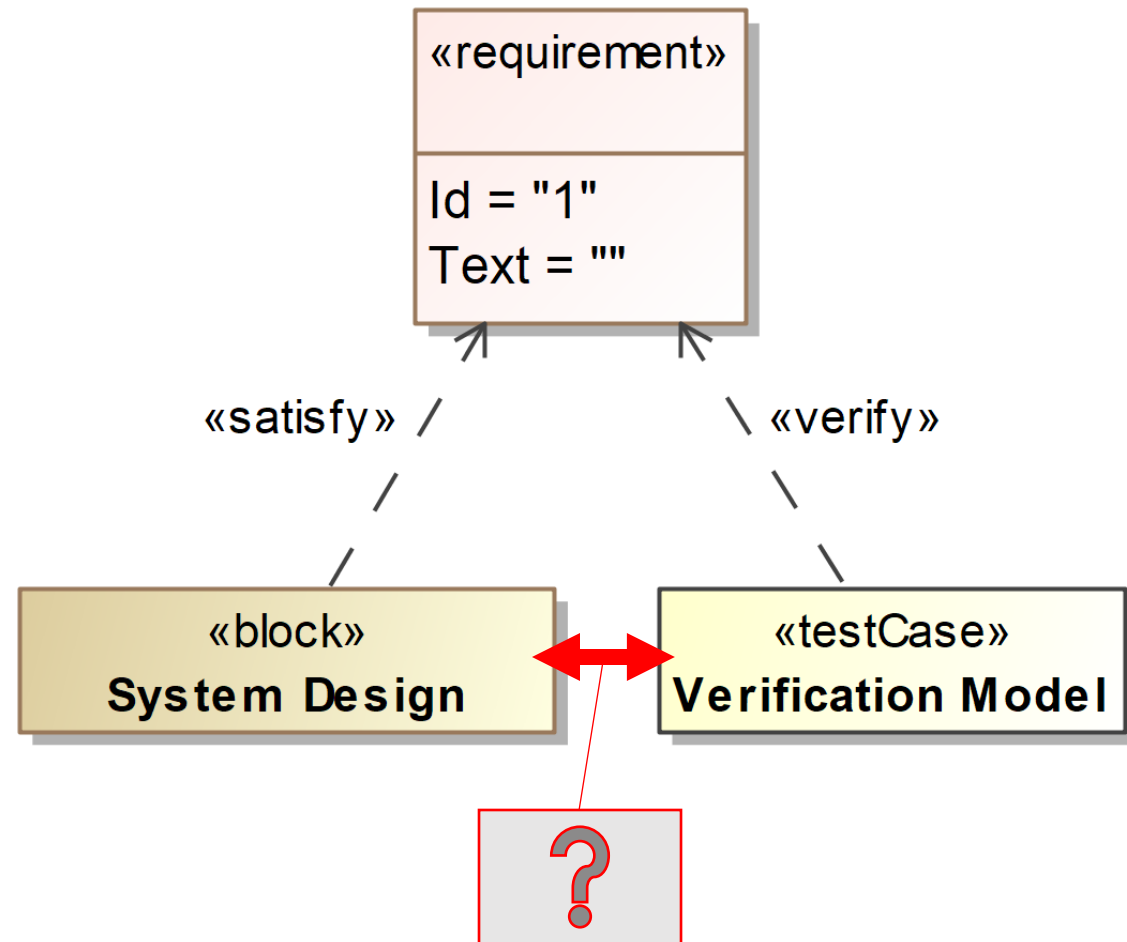
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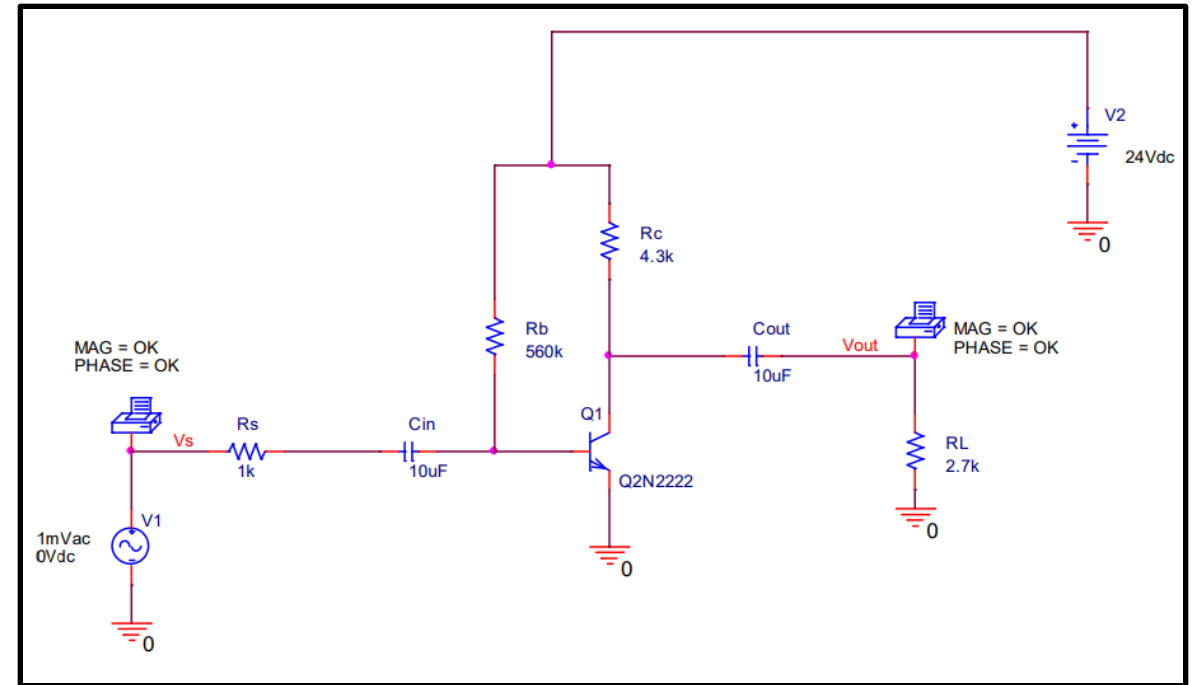
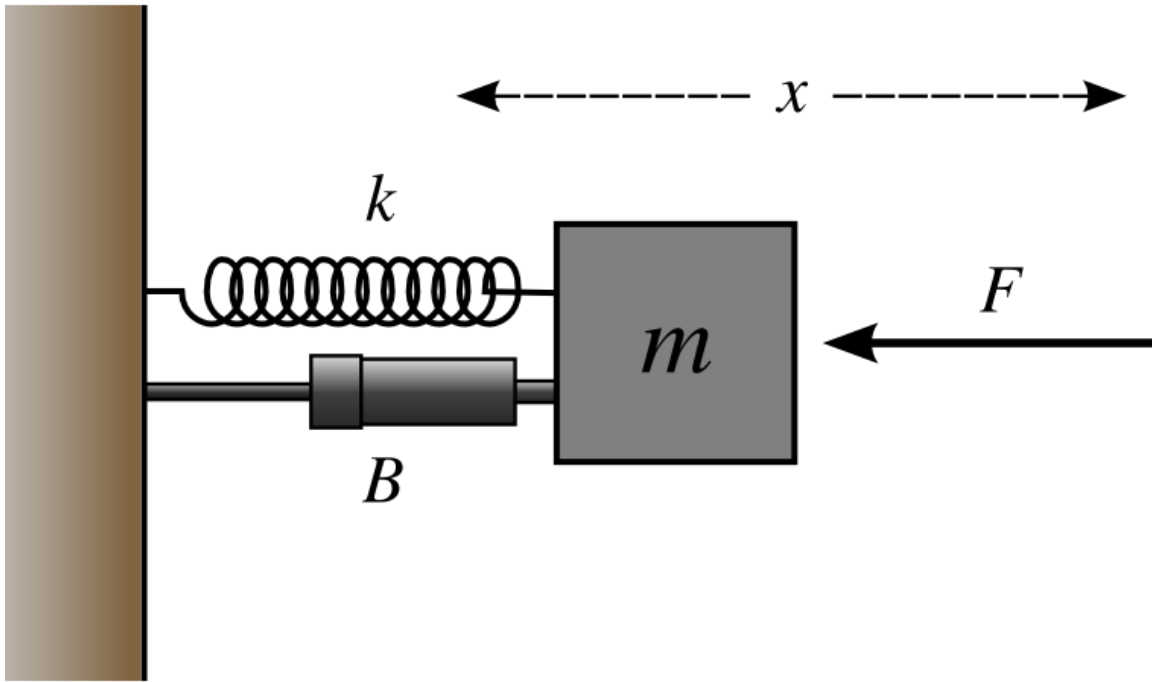
^ Finite element analysis ^

# How does Systems Engineering Maturity Compare to Other Engineering Domains?

- Current forms of Model-Based Systems Engineering (MBSE) are descriptive and do not have theoretical foundations
- A systematic literature review of ~2,000 articles suggests that theoretical foundations for MBSE are nascent

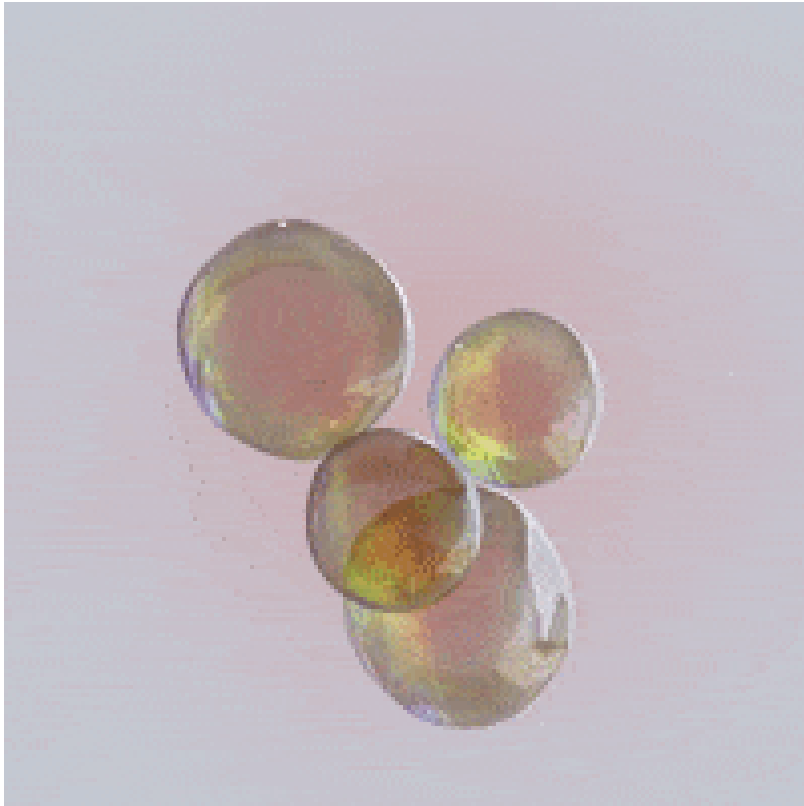


# Example of Rich Mathematical Foundations for Systems Engineering to Draw Upon



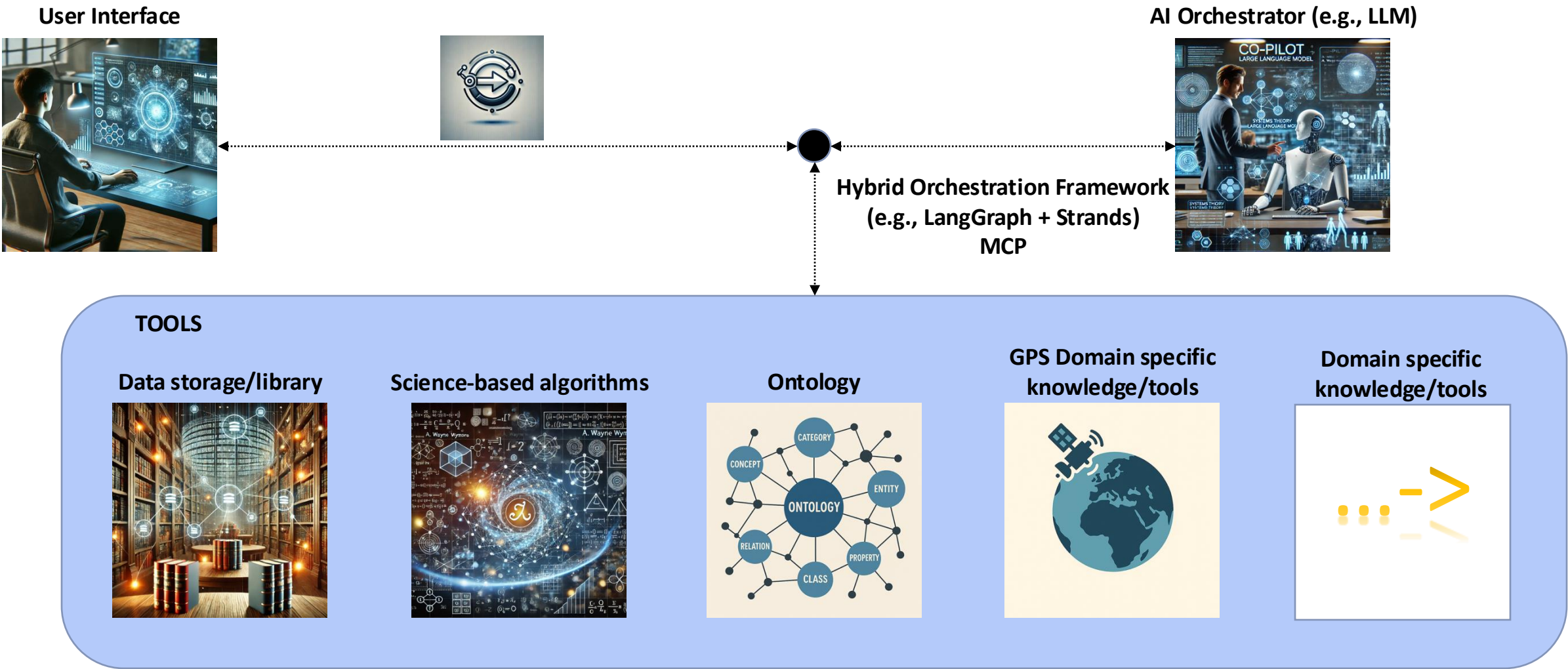
Well-known equivalence between a  
mechanical mass-spring (left)  
and  
electric circuit (right)

# Example of Rich Mathematical Foundations for Systems Engineering to Draw Upon



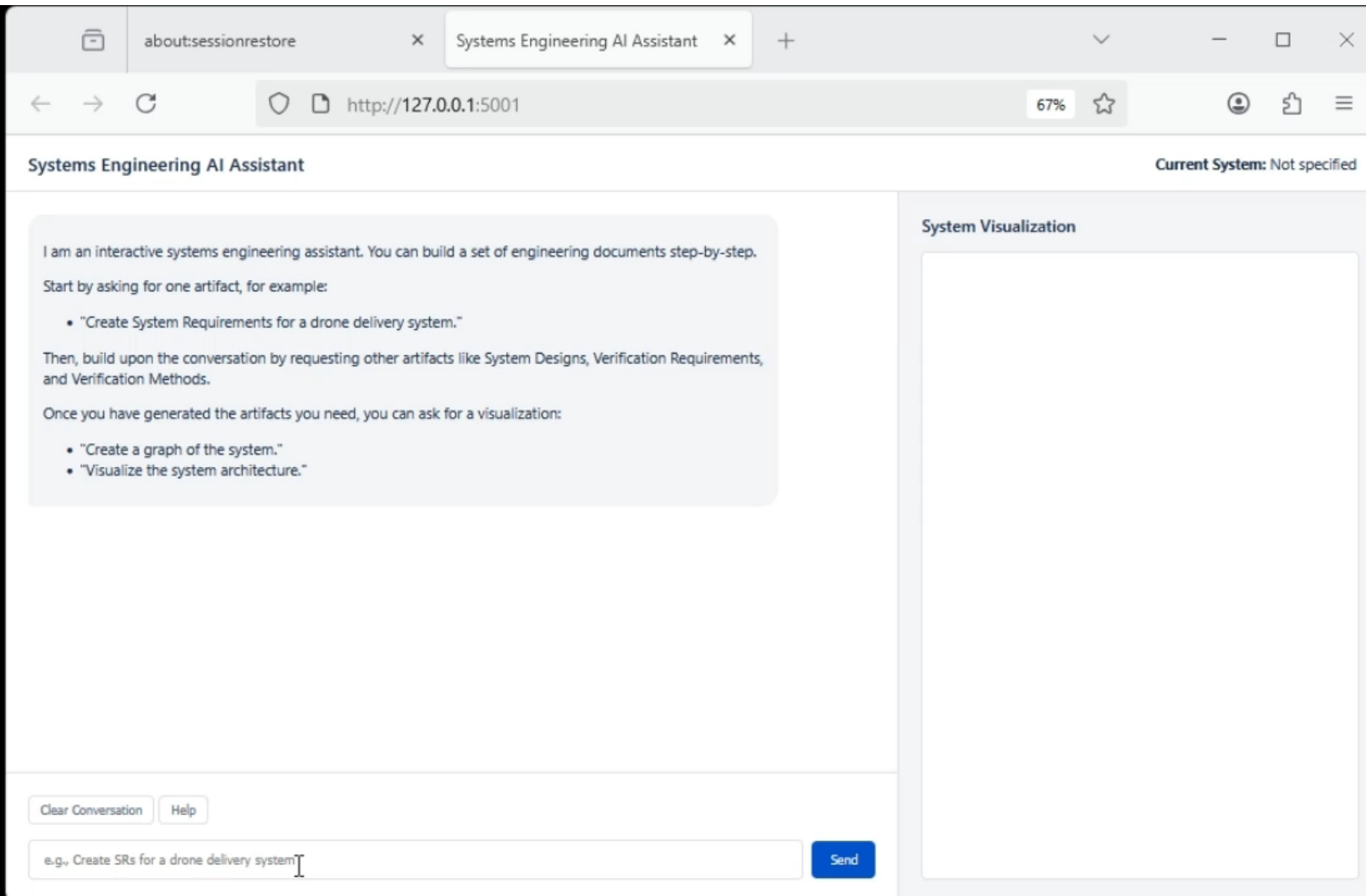
Less-known equivalence between a  
Micro-/nanofluidic bubble (left)  
and  
Capacitor (~right)

# Shifting to Agentic AI for the Co-Pilot

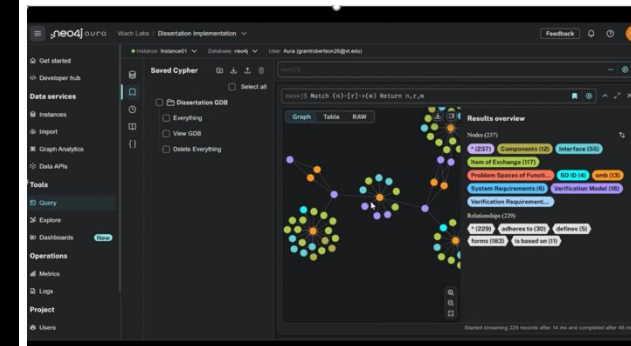




# Demo Video 2: Current State of the Co-Pilot

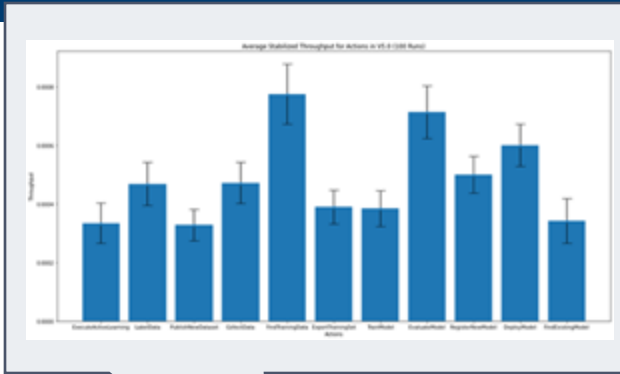


Kudos to  
**Aditya (Adi) Iyer** and  
**Grant Anderson**



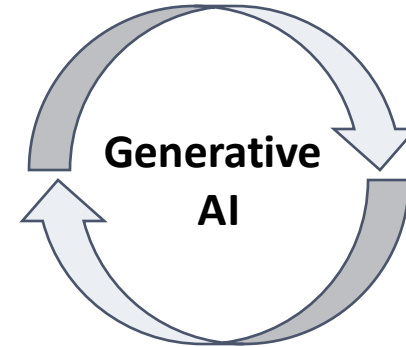


# Discrete Event System Specification (DEVSS)



Analysis and Design Optimization

System Requirements and Operation Environment

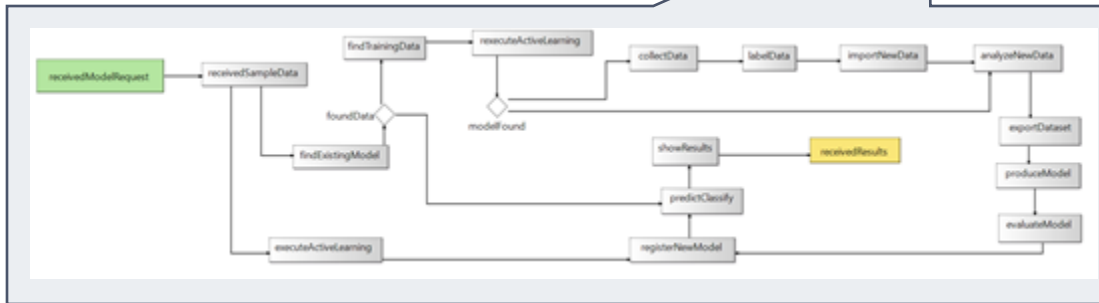


Functional System Architecture

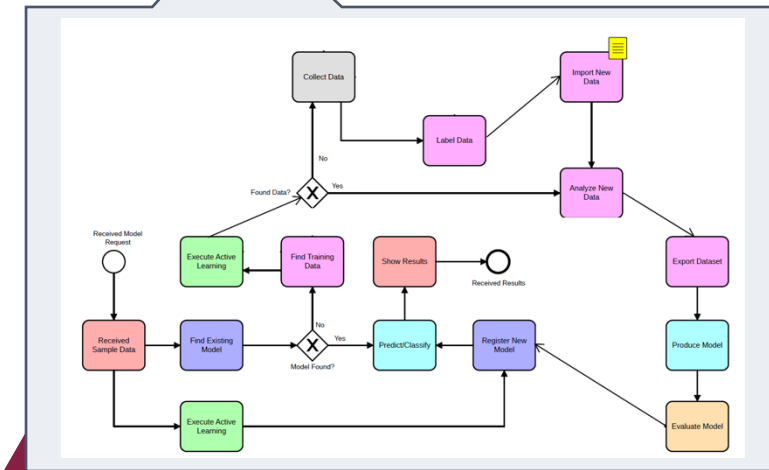
Modeling and Simulation

**Integration Support Linking of High-Level Architecture Products and Downstream Models and Simulators**

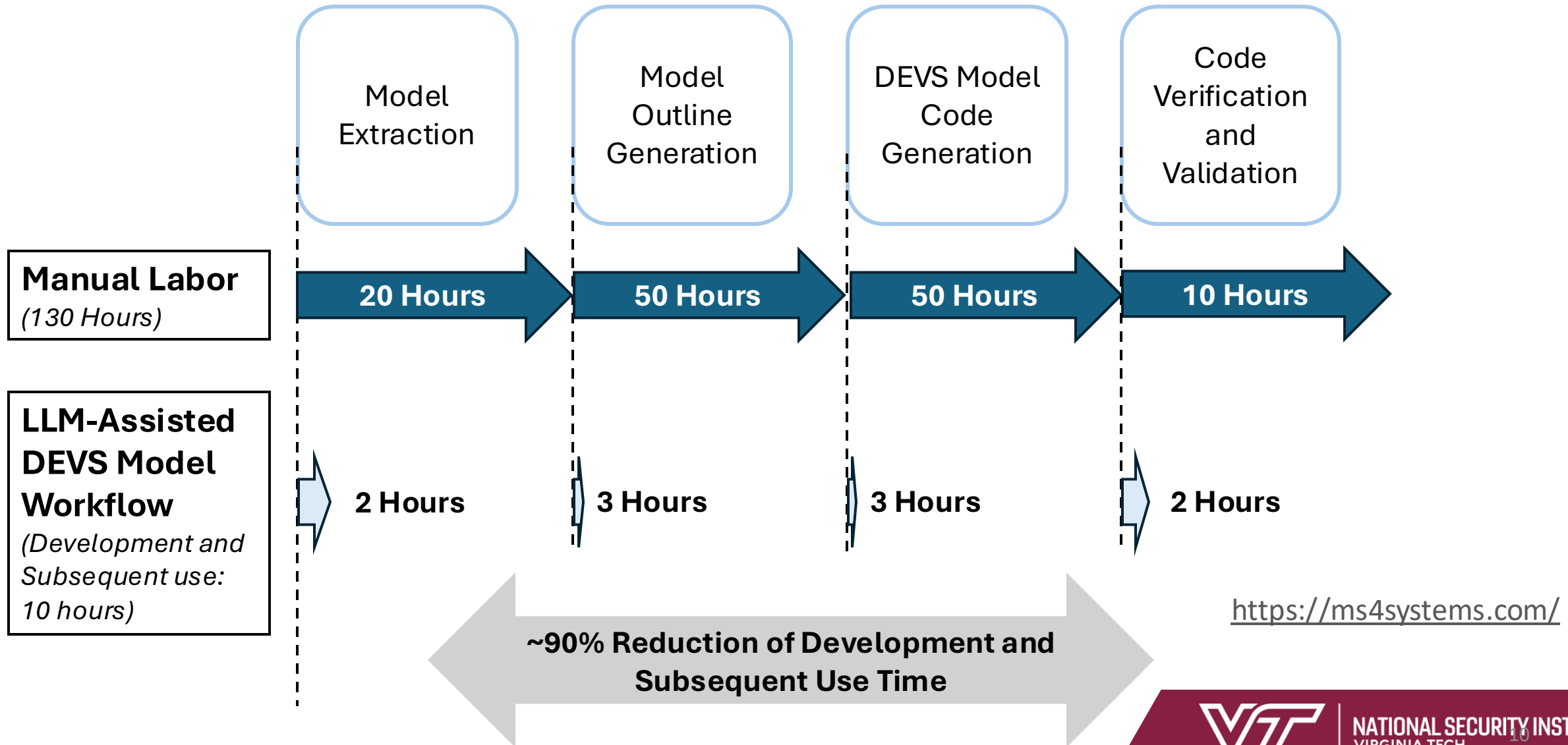
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# Demonstrated Efficiency Gain



# Rapid Development of Neural Swarm-Optimized Kill Chain Analytics

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## Introduction and Indo-Pacific Context

Modern military operations in the Indo-Pacific theater demand unprecedented speed and integration across domains. The canonical kill chain — Find, Fix, Track, Target, Engage, Assess (F2T2EA) — must be executed against fast-moving threats (e.g., hypersonic missiles, mobile launchers) in compressed timeframes [1][2]. Adversaries such as China are fielding a resilient *kill web* of networked sensors and shooters, especially in space, to shorten their own kill chains. For instance, China's kill web links hundreds of ISR satellites directly to terrestrial strike units, enabling targeting and engagement within seconds [3]. U.S. Space Force officials warn that this satellite-enabled web can find, fix, and track U.S. forces over vast distances, posing a grave threat in the Indo-Pacific region [3][4].

This page implements the paper's core model: a probabilistic treatment of the sequential F2T2E process following Rice's framework, plus sensitivity analysis, with a focus on Indo-Pacific kill-web implications.

## Probabilistic Modeling of F2T2E

Let the times to complete each phase be independent exponentials:  $t_i \sim \text{Exp}(\lambda_i)$  with mean  $\theta_i = 1/\lambda_i$  for  $i = 1, \dots, 5$  corresponding to Find, Fix, Track, Target, Engage [1][2]. The kill chain succeeds by time  $T$  iff the sum  $S = \sum_{i=1}^5 t_i \leq T$ . For distinct rates, the hypoexponential CDF is:

$$P_{F2T2E}(T) = 1 - \sum_{i=1}^5 \left( e^{-\lambda_i T} \prod_{j=1, j \neq i}^5 \frac{\lambda_j}{\lambda_j - \lambda_i} \right),$$

with  $\lambda_i = \frac{1}{\theta_i}$  and Erlang CDF used if all  $\lambda_i$  equal.

We expose an interactive calculator (right column) to evaluate  $P_{F2T2E}(T)$ , visualize it across a chosen time window, and estimate finite-difference sensitivities  $\partial P / \partial \theta_i$  at a specified  $T$  (sign indicates whether increasing  $\theta_i$  helps or hurts overall success) [1].

## Kill-Web Elasticity (Parallel Sensors)

If multiple independent assets contribute to the same phase (e.g., parallel Find sensors), effective rate increases additively:  $\lambda_{\text{Find,eff}} = \sum_k \lambda_{\text{Find}}^{(k)}$ . This reduces  $\theta_{\text{Find}}$  and lifts  $P_{F2T2E}(T)$ , expressing the resilience and elasticity of kill webs under redundancy.

## Notes on DEVS & MDP (Structure Only)

The full DEVS/MDP swarming architecture from the paper is structural and simulation-oriented. This HTML focuses on the analytically evaluable component  $P_{F2T2E}(T)$  and its sensitivities. For formal details, see [5] (hierarchical MDPs in DEVS) and [6] (DEVS+model-checking).

## Model Workspace

F2T2E Calculator    DEVS/MDP Formal Details

### Interactive F2T2E Calculator Live

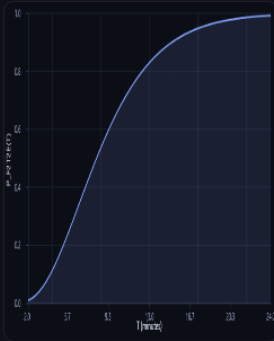
$\theta_1$ (Find) [min]	$\theta_2$ (Fix) [min]	$\theta_3$ (Track) [min]
3	2.5	2
$\theta_4$ (Target) [min]	$\theta_5$ (Engage) [min]	Sensitivity at T [min]
1	0.5	12.35
Plot $T_{\min}$ [min]	Plot $T_{\max}$ [min]	Plot points
2	24	200

Parallel Find Assets (optional)

0    3    **Apply to  $\theta_1$ .**    **Reset  $\theta_1$ .**

**Compute & Plot**    **Load Indo-Pacific Example (Fig.-like)**

**Export CSV**



### Point Calculation

$P_{F2T2E}(12.350 \text{ min}) =$   
0.800168  
Lambdas: [ 0.333333,  
0.400000, 0.500000, 1.000000,  
2.000000 ] min<sup>-1</sup>

### Finite-Difference

**Sensitivities**  
( $\Delta P_{F2T2E} / \Delta \theta_i$ )

Phase ( $\theta_i$ )	dP/d $\theta_i$ @ T
$\theta_1$ (Find)	-7.011987e-2
$\theta_2$ (Fix)	-6.957789e-2
$\theta_3$ (Track)	-6.783697e-2
$\theta_4$ (Target)	-5.996014e-2
$\theta_5$ (Engage)	-5.450264e-2

Negative values mean decreasing  $\theta_i$  (speeding phase i) increases overall success.

Live demo



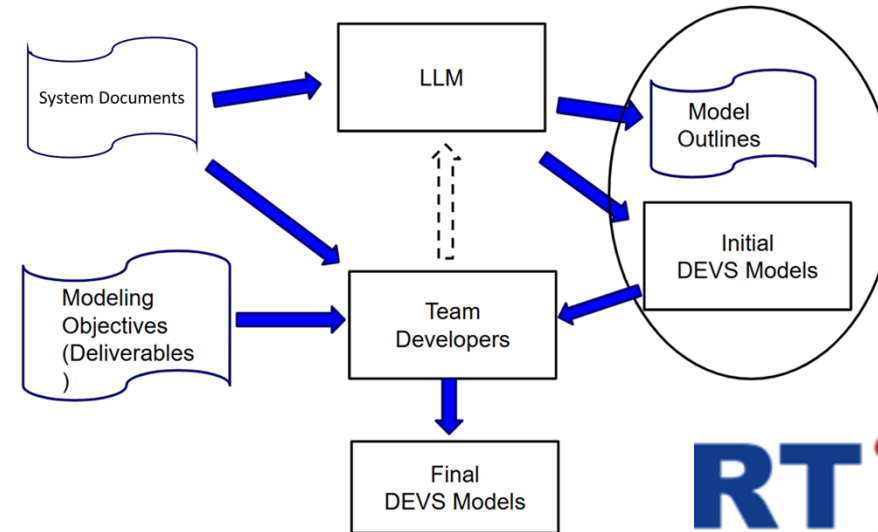
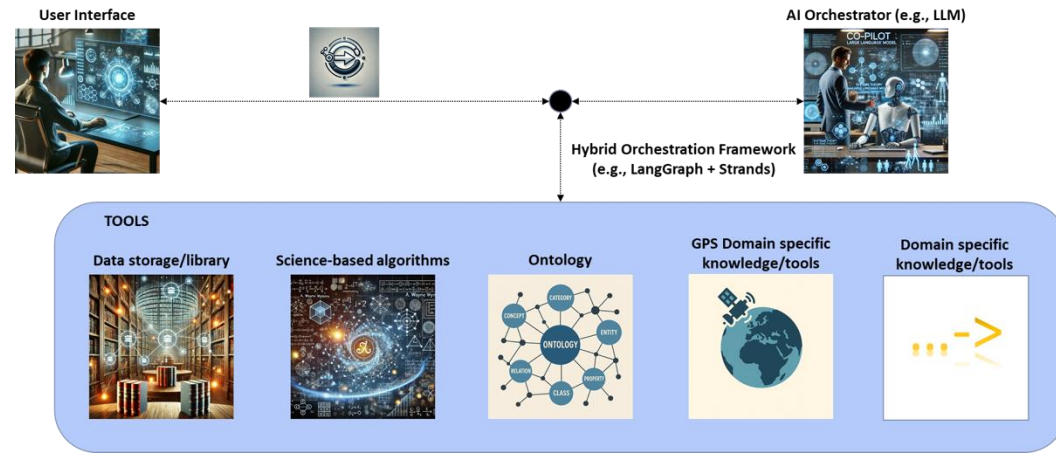
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# Concluding Summary

➤ **Main theme:** mathematically underpinned methods and tools enable both efficiency and effectiveness

➤ Demos shown:

- ✓ Systems Engineering assistant focused on system requirements, system design, and verification
- ✓ Modeling & Simulation efficiency gains and use for kill chain analysis



**RTS**ync

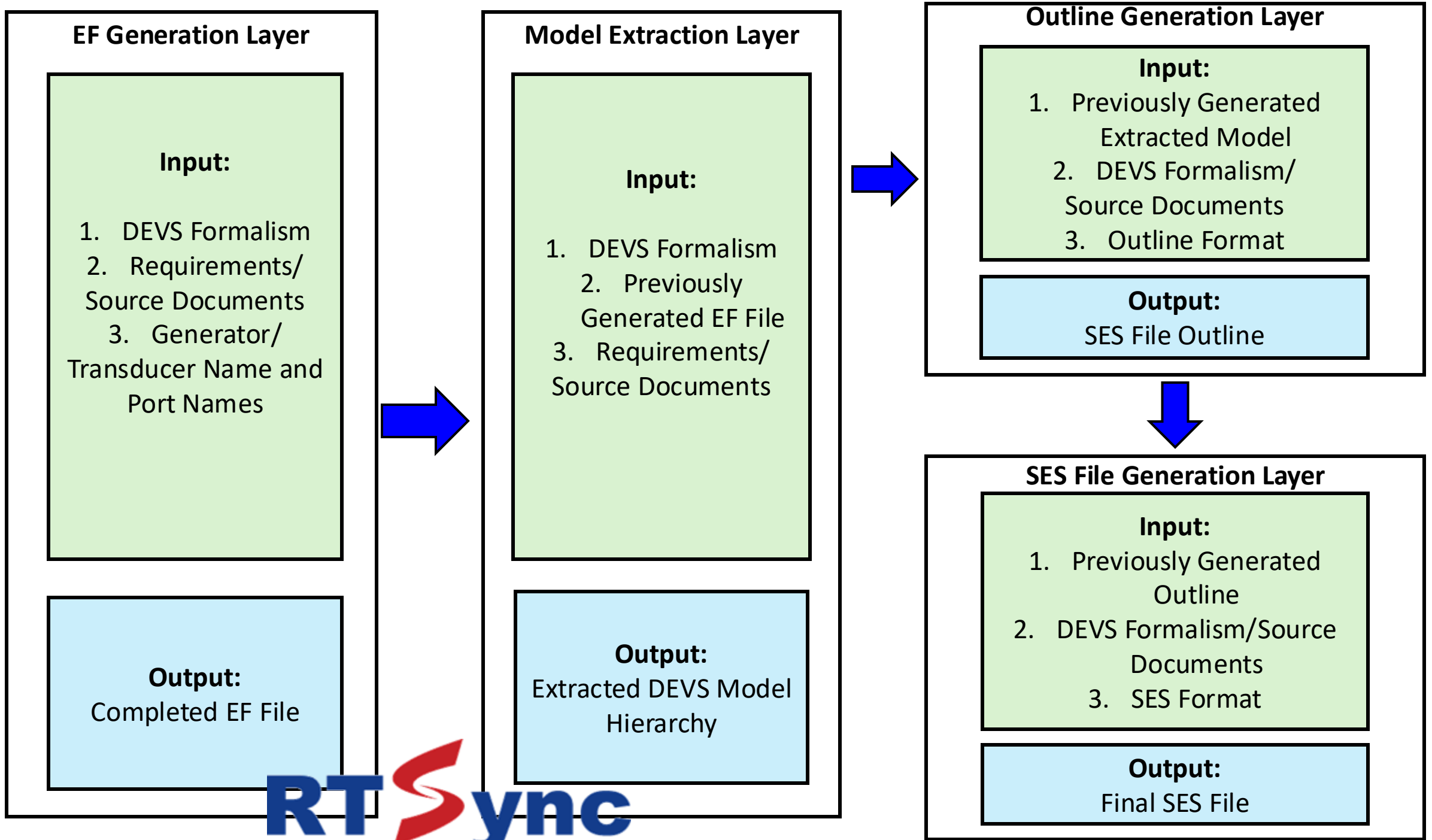


# Questions?

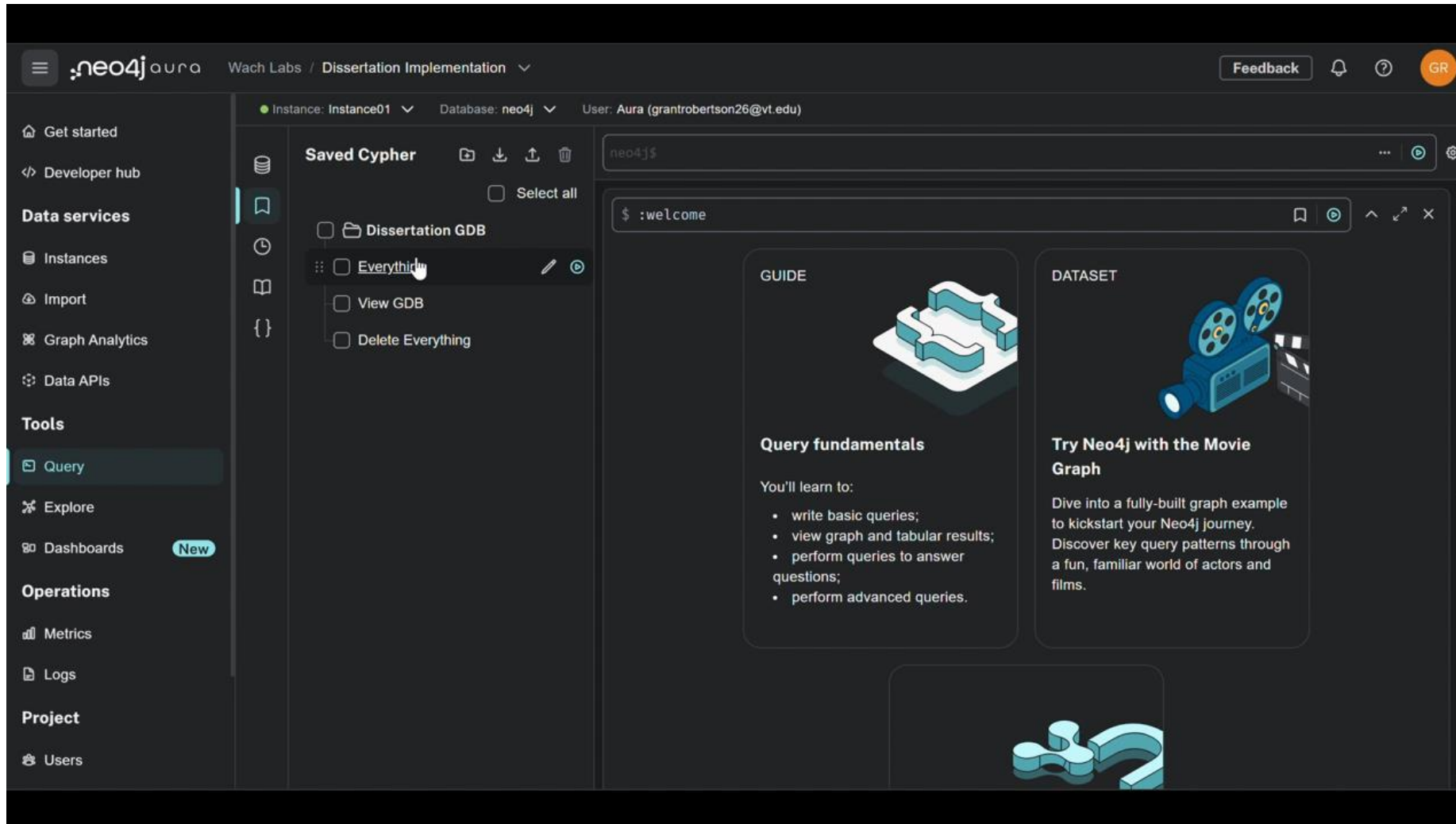
Contact:

Paul Wach, [paulw86@vt.edu](mailto:paulw86@vt.edu)





# DEMO Video 1: Graph Database (Neo4j)



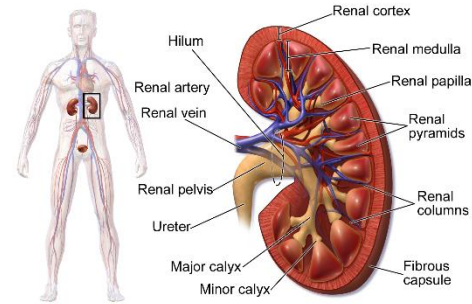
Enables **enhanced data analysis** and increased rigor **data structures**, based on **ontological foundations**

Kudos to  
**Grant Robertson**,  
Summer volunteer  
Industrial & Systems  
Engineering rising senior,  
expected graduation  
May 2026



# Who is Paul? (or Professor Paul or Doc Wach)

BS in Biomedical Engineering 2009



Kidney Anatomy



MS in Mechanical Engineering 2013



PhD in Industrial and Systems Engineering 2022



Research Faculty in Intelligent Systems  
Division 2023-present



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