

New Observing Strategies Testbed (NOS-T) Design and Development

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Presentation Overview

- Context and Background
 - NASA's Earth Science Program
 - New Observing Strategies (NOS)
- NOS Testbed Framework
 - Development Principles
 - Concept of Operations
 - Governance
 - > System Architecture

- Example Application Cases:
 - Simulated Mission
 - ➢ Real-time Mission
 - Tasking/Collecting Demonstration
- Technical Architecture
 - > Event-driven Architecture
 - > Application Interfaces

Earth Science Decadal Survey Strategy Elements

- 1. Sustained Science and Applications
- **2.** Innovative Methodologies
- 3. Cross-Benefit of Science and Applications
- 4. External Resources and Partnerships
- 5. Programmatic Agility and Balance
- 6. External Trends
- 7. Competition
- 8. Ambitious Science and Applications

THRIVING ON OUR CHANGING PLANET A Decadal Strategy for Earth Observation from Space

The National Academies of SCIENCES - ENGINEERING - MEDICINE



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New Observing Strategies (NOS)



- **Optimize** measurement acquisition using diverse observing capabilities
- **Observe** phenomena from different spatial, temporal, and spectral vantage points
- Coordinate observations based on events, forecasts, or science models
- Leverage NASA and non-NASA assets and data sources

NOS Testbed (NOS-T) Programmatic Objectives



- Validate NOS technologies independently and as a system
- **Demonstrate** new distributed operational concepts
- Enable comparisons of competing technologies
- **Socialize** new technologies and concepts with the science community and reduce risk

NOS-T Design and Development Objectives

- Enable disparate organizations to propose and participate in developing NOS software and information tech using the Testbed
- NOS-T Framework Architecture:
 - ➤ Governance
 - Concept of Operations
 - > Technical Protocols and Interfaces
- Iteratively develop prototypes and demonstrate NOS-T operation for a representative Earth science mission with at least three nodes
 - Version 1.0 (18 months ending February 2022)
 - Version 2.0 (18 months ending August 2023)

NOS-T Framework: Governance



NOS-T Framework: Concept of Operations

NOS-T Framework: Technical Principles

Geographic distribution:

user applications interconnect using standard network interfaces

Multi-party participation:

user applications exchange limited information via standard messaging protocols

Security: encrypt transport data, provide fine-grain access control rules, monitor hosted infrastructure on authorized information systems **Modularity**: loose coupling allows components to be added or updated without modifying the testbed

Extensibility: vary the number or capabilities of user applications to explore a wide range of test cases

Usability: allow members of the Earth science community to develop test cases and user applications without a substantial learning curve

NOS-T Graphical Concept

Event-driven Architecture

- Applications communicate state changes via *events* (messages)
 - Published to topics
 - Event broker notifies all subscribers
- Broker: Solace PubSub+ Standard
 - MQTT messaging protocol
 - Up to 1000 concurrent connections and 10,000 messages/second
 - Hosted on the Science Managed Cloud Environment (SMCE), a FISMA Low cloud information system

Application Case 1: Simulated Time Execution

- Investigate fire hazard detection in the continental U.S.
 - > Initiate fires using 2020 VIIRS data
 - Remote observation by threesatellite constellation
 - Data downlink to ground station
 - Evaluation of key performance measures (observation latency)
- Extensible to design-ofexperiment studies to assess observation system variables

5-day (at 60x Scale) Scenario; Playback Speed ~90x

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FireSat+ Test Case Architecture

- **Fires:** publishes fire location, records times started, detected, reported
- **Ground:** publishes ground station location
- Satellites: models orbit propagation, detects fires, reports fires when link to Ground is possible
- **Scoreboard:** displays graphical representation of mission

FireSat+ Interface Sample

- Topic:
 - nost-001/fires/location
- Payload:
 Fire ID, ignition lat/lon, timestamp
- Topic:
 - > nost-001/satellite/detected
 - > nost-001/satellite/reported
- Payload:
 - Fire ID, satellite ID, timestamp, state

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NOS-T Technical Interface

Application Case 2: Real-time Test Case

- Real-time stream gauge data retrieved via web requests from the USGS National Water Information System (NWIS)
 - Displays flow rates from two sensors on a dashboard – Mississippi River above and below Minneapolis/St. Paul
 - Demonstrates ability to use real-time data for a test case
- Extensible to trigger spacecraft observations when certain flow rates are met

Real-time Case: Application Architecture

15-hour (real-time) scenario; 2000x playback

Application Case 3: NOS-Live (NOS-L) Demonstration

- Design and demonstrate an event-driven architecture to automatically task, collect, and integrate data products into forecasts
- Essentially a four-node problem:
 - Science application identifying area of interest (Lon, Lat, time window) – NASA GSFC
 - Tasking application to interface with commercial satellite provider API – NASA JPL
 - Commercial satellite providers with automated API interface
 - Data transfer application to move collected data products to correct location – Stevens

Tasking Sequence Diagram (Capella)

LIS/GEFS sted on DISCOVER)	NOS-T Message	Tasking	Application		Capella	a API
	Broker (EC2 Instance)		POST: Token Request (url, headers, <u>auth)</u> Response: accessToken, refreshToken, expiresIn		,	
Neede (optior	Needed for Task Request: Name, Description (optional), Coordinates, window (open, close), priority			: Task Request n bearer token, json boc e: taskingrequestld	dy)	
	Keeping Track of Orders/Costs: taskingrequestId, order cost NOTE: PATCH unnecessary if preApproved = TRUE		GET: Tas (url with taskingred	sk Request Status questld, headers with be token)	earer	
			Response: statusHistory code = 'review' (order cost summary)			
			PATCH: Approve Request (url with taskingrequestId, headers with bearer token, json = {"status":"approved"})			
			GET: Tas (url with taskingred	GET: Task Request Status (url with taskingrequestId, headers with bearer token)		
			Response: statusHistory code = 'completed'			2
			GET: Collections List (url with taskingrequestId, headers with bearer token)		Trigger Manual Workflow for SWE Product	
Finish	ned Task: tasking/comple	ted, collect_id	Response: or	rderld, collectId, granule	eld	

Data Access Sequence Diagram (Capella)

Amazon Web Services: Supporting Architecture

Summary

- NOS-T provides computational platform to prototype NOS missions
- NOS-T framework provides an initial governance model, concept of operations, and technical interface specification
 - > Event-driven architecture
 - Simulated and real-time execution
- NOS-T Tools Python library available under an open-source license:
 - Repository: <u>https://github.com/code-lab-org/nost-tools</u>
 - Documentation: <u>https://nost-tools.readthedocs.io/en/latest/</u>

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THANK YOU

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