

# Game-theoretic Risk Assessment for Distributed Systems (GRADS)

**Sponsor: DASD(SE)**

**By**

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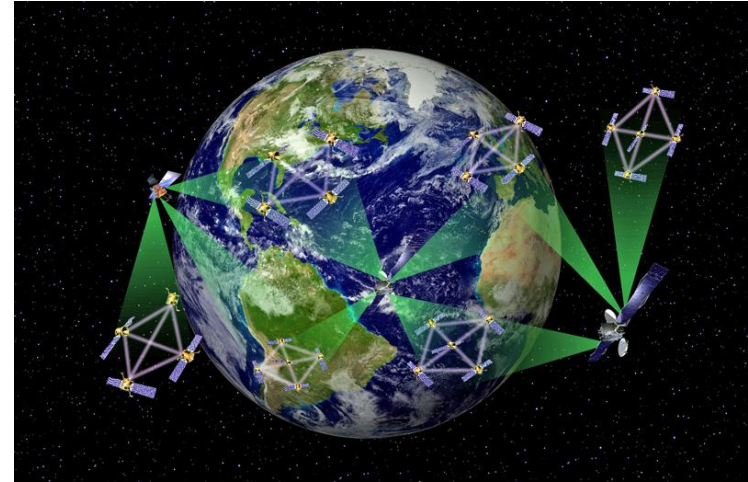
- Problem Statement
- Research Questions
- Foundations: Stag Hunt Game and Risk Dominance
- Research Plan: Application to NPOESS Scenario
- Conclusion and Future Work

## Upside Potential

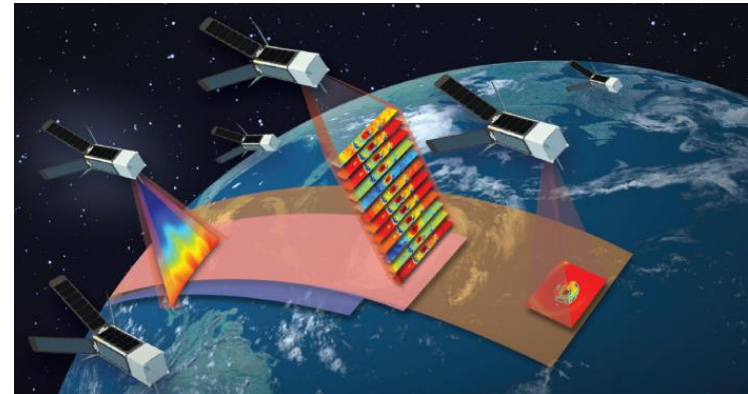
- Flexibility, robustness
- Mission effectiveness
- Resource efficiency

## Downside Risk

- Interdependencies
- Complex behavior
- Cascading failures



System F6 Concept (DARPA)



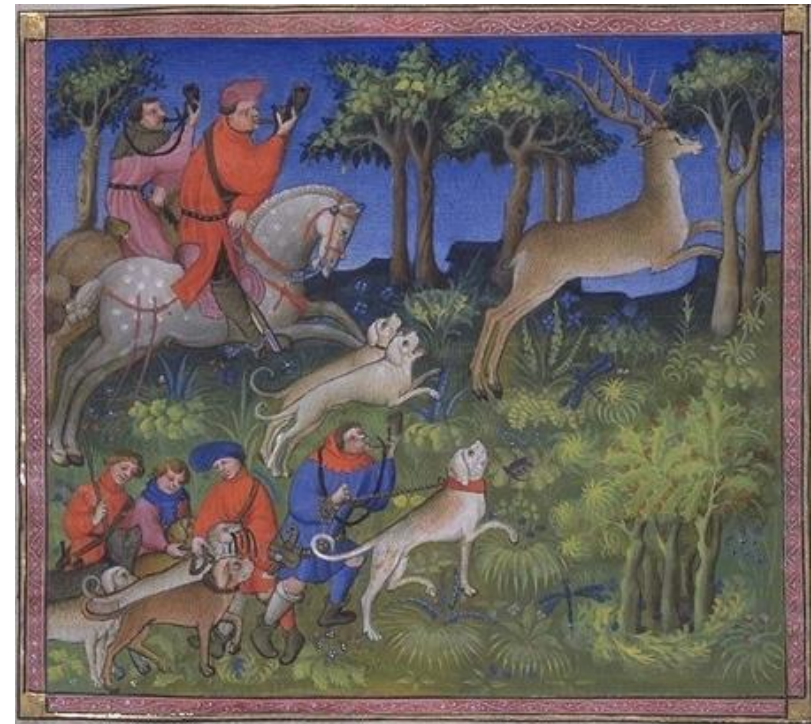
TROPICS Mission Concept (NASA, Lincoln Labs)

- Future complex engineered systems will have more **distributed architectures** with decentralized decision-making among multiple independent design actors
- Two types of risk in collaborative projects:
  - **Systemic risk**: cost, schedule, and technology uncertainty
  - **Collaborative risk**: conflict and coordination failures
- Need improved methods to assess collaborative risk
  - Identify and avoid poor strategic dynamics early
  - Improve strategic decision-making to balance efficiency (feasibility), effectiveness (desirability), and stability (viability)

- **How to assess collaborative risk in distributed systems?**
  - Tradeoff between expected upside and possible downside
  - Collaborative risk linked to decision stability, not uncertainty
  - Evaluate an objective risk metric based on Selten's (1995) Weighted Average Log Measure (WALM) of risk dominance
- **How can a collaborative risk metric be operationalized to evaluate a realistic joint program proposal?**
  - Develop scenario narrative following National Operational Polar-orbiting Environmental Satellite System (NPOESS) program
  - Assess collaborative risk for a joint project between Department of Defense (DoD) and National Atmospheric and Oceanic Administration (NOAA)

	Hare	Stag
Hare	2, 2	4, 0
Stag	0, 4	5, 5

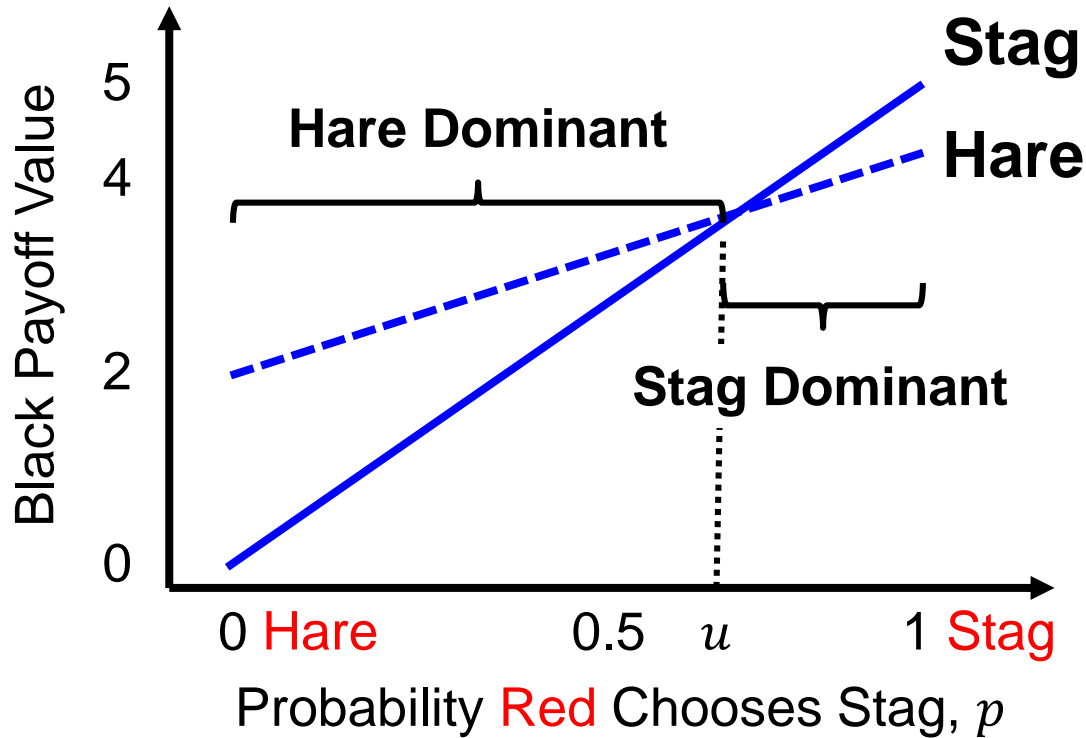
- Cell entries measure actor payoff/utility/value
- Two pure Nash equilibria
  - Hare, **Hare**: risk-dominant equilibrium (minimize risk)
  - Stag, **Stag**: payoff-dominant equilibrium (maximize reward)



*Cy deute comment ou doit aler laister pour le cerf* ©Bibliothèque nationale de France

Stag hunt by Gaston Phoebus  
(Bibliothèque Nationale de France)

# Stag Hunt Under Uncertainty



	Hare	Stag
Hare	2 2	4 0
Stag	0 4	5 5

- $p > u$ : choose stag option,  $p < u$ : choose hare option

- $u$ : Normalized deviation loss,  $u = \frac{(2-0)}{(2-0)+(5-4)} = \frac{2}{3}$

- Proposed by Selten (1995) to meet a set of desirable axioms
  - Normative for rational actors
  - Purely objective (assumes  $p = 0.5$ )

- $n$ -player general case:

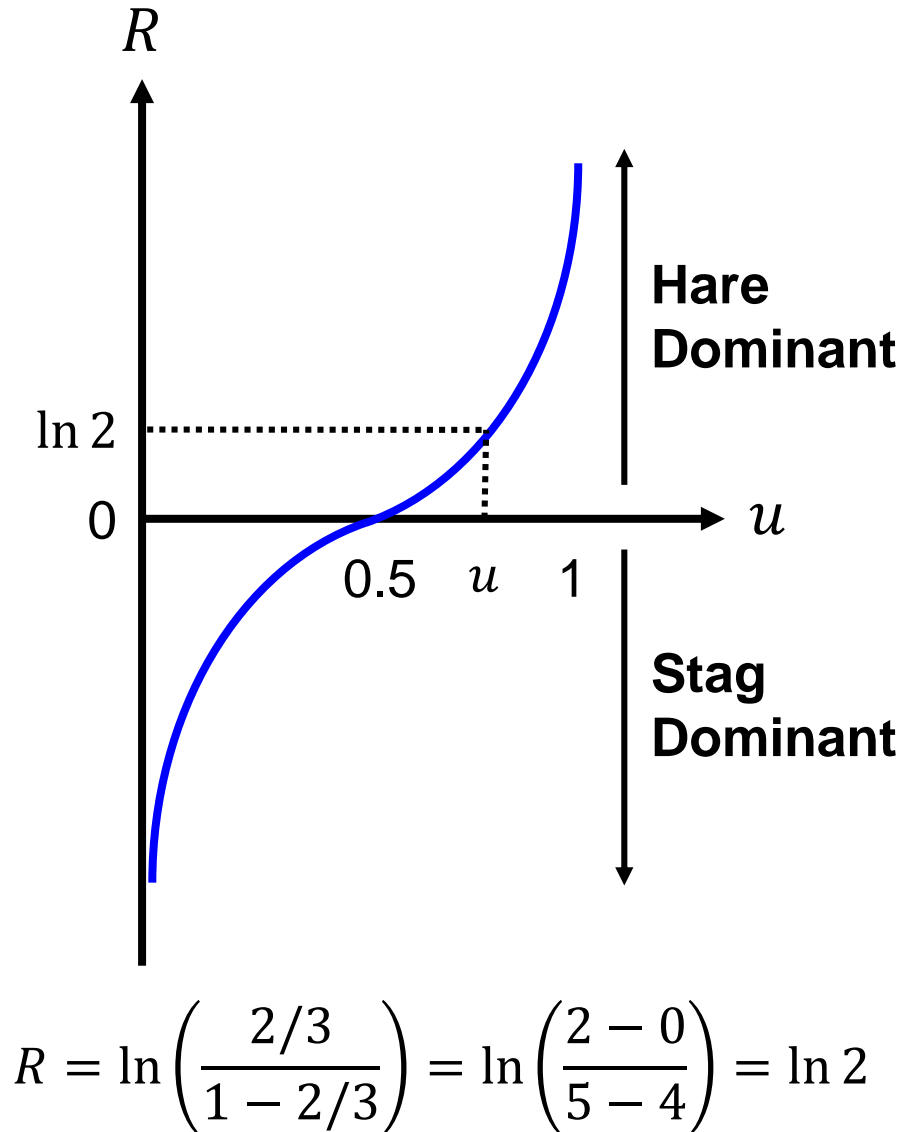
$$R = \sum_{i=1}^n w_i(A) \ln \left( \frac{u_i}{1 - u_i} \right)$$

- 2-player asymmetric case:

$$R = \frac{1}{2} \ln \left( \frac{u_1}{1 - u_1} \right) + \frac{1}{2} \ln \left( \frac{u_2}{1 - u_2} \right)$$

- 2-player symmetric case:

$$R = \ln \left( \frac{u}{1 - u} \right)$$





- Engineering requires two levels of design decisions:
  - Strategy: long-term policy (collaboration or independence)
  - Design: architecture to maximize value in strategic context

- Strategy space:

$$\mathcal{S} = \{\underline{\text{Stag}}, \underline{\text{Hare}}\}$$

- Design space:

$$\mathcal{D} = \{\underline{\text{Axe}}, \underline{\text{Bow}}, \underline{\text{Club}}, \underline{\text{Dog}}, \dots\}$$

- Multi-actor value function:

$$V^{s_1, s_2}(d_1, d_2): \mathcal{D}^2 \times \mathcal{S}^2 \rightarrow \mathbb{R}^2$$

	Hare	Stag
Hare	$V_1^{HH}(B, B) = 2$ $V_2^{HH}(B, B) = 2$	$V_1^{HS}(B, D) = 4$ $V_2^{HS}(B, D) = 0$
Stag	$V_1^{SH}(D, B) = 0$ $V_2^{SH}(D, B) = 4$	$V_1^{SS}(D, D) = 5$ $V_2^{SS}(D, D) = 5$

- Dog is selected “design” to execute Stag “strategy”
- Bow is selected “design” to execute Hare “strategy”
- Other designs could be tested

- Two general approaches to reduce collaborative risk:

## 1. Increase upside potential

- Increase benefit of collaboration
- Better design to hunt stag *together*
- Maximize denominator of  $R$

- Fundamental problem:

*robust-yet-fragile* behaviors

- Highly-optimized stag hunt design trades context-specific value for fragility
- Example: coordination overhead, mutual dependence

	Hare	Stag
Hare	2	4
Stag	0	5

Red numbers (2, 0, 4, 5) are placed in the bottom-right quadrant of each cell. Blue dashed ovals highlight the (Hare, Stag) and (Stag, Stag) cells.

$$R = \ln \left( \frac{2 - 0}{5 - 4} \right) = \ln 2$$

- Two general approaches to reduce collaborative risk:

## 2. Decrease downside risk

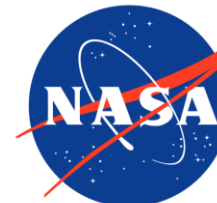
- Reduce penalty of coordination failure
- Better design to hunt stag *alone*
- Minimize denominator of  $R$
- Reflects principle of *stable intermediate forms*
  - Reduce coordination overhead
  - Establish independent source of value regardless of coordination outcome

	Hare	Stag
Hare	2	4
Stag	0	5

*Note: In the original image, a blue dashed oval highlights the values 2 and 0 in the first column of the matrix.*

$$R = \ln \left( \frac{2 - 0}{5 - 4} \right) = \ln 2$$

- Study how concepts of collaborative risk dominance can be applied to a realistic systems design problem
- Retrospective study of National Polar-orbiting Operational Environmental Satellite System (NPOESS)
  - Proposed joint program between the U.S. Department of Defense (DoD) and U.S. Department of Commerce/National Oceanic and Atmospheric Administration (NOAA)
  - Incorporate instruments developed under the National Aeronautics and Space Administration (NASA) Earth Observing System (EOS) program
  - Motivated by resource efficiency (cost savings)



# NPOESS Background



Polar-orbiting Operational  
Environmental Satellite (POES)



Defense Meteorological  
Satellite Program (DMSP)



Earth Observing  
System (EOS)



Joint Polar Satellite  
System (JPSS)



Defense Weather Satellite  
System (DWSS)



National Polar-orbiting  
Operational Environmental  
Satellite System (NPOESS)



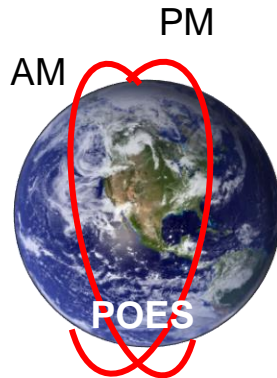
Weather System  
Follow-on (WSF)

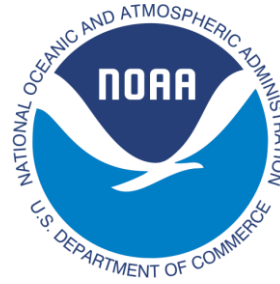


1960s 1970s 1980s 1990s

2000s

2010s













	POES	NPOESS
DMSP	DMSP POES	DMSP (JPSS)
NPOESS	(DWSS) POES	NPOESS NPOESS

- Model alternative architectures/designs:
  - 2 baseline independent systems: DMSP, POES
  - 1 successful collaborative system: NPOESS
  - 2 “coordination failure” systems: *DWSS/WSF*, *JPSS*
- Simulate key performance attributes: measurements, revisit period, data latency, data volume, cost
- Model actor preferences (multi-actor value)
  - Subjective preferences and weights for each attribute
  - Aggregate preferences for each design alternative
  - Inherently subjective, many simplifying assumptions

# Anticipated Results (Idealized)



	POES	NPOESS
DMSP	<p>\$ #</p>  <p>- ▲ +</p> <p>\$ #</p>  <p>- ▲ +</p>	<p>\$ #</p>  <p>- ▲ +</p> <p>\$\$ #</p>  <p>- ▲ +</p>
NPOESS	<p>\$\$ #</p>  <p>- ▲ +</p> <p>\$ #</p>  <p>- ▲ +</p>	<p>\$ ##</p>  <p>- ▲ +</p> <p>\$ ##</p>  <p>- ▲ +</p>

\$: Unit of Cost  
#: Unit of Value





- NPOESS program experienced substantial *systemic risk*, specifically cost growth studied by others
  - Goal is *not* to provide retrospective analysis or “hotwash”
  - Leverage large volume of information availability and academic/government reports
  - Purposefully simplify context and scenario for tractability
- This study focuses solely on *collaborative risk*
  - Use context of NPOESS to evaluate the usefulness of the proposed collaborative risk assessment methodology
  - Communicate and validate results of an analysis process

- Two types of risk in collaborative projects:
  - **Systemic risk:** cost, schedule, and technology uncertainty
  - **Collaborative risk:** conflict and coordination failures
- Investigate Selten's risk dominance measure to assess collaborative risk from a game-theoretic perspective
- Demonstrate with application case based on NPOESS
  - Define design space under collaborative/independent scenarios
  - Model performance attributes for each design
  - Model value preferences for each actor
  - Assess risk dominance for strategic design game

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  - Henry Lee, M.E. Student in Space Systems Engineering
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