

# ***Air Force Institute of Technology***

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*Integrity - Service - Excellence*

## ***AFIT SE Research***



**U.S. AIR FORCE**

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**Dr Dave Jacques**

**Dr John Colombi**

**Dept of Systems and Engineering Mgt**

**AFIT/ENV**



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# DoD Transformation Drives Research



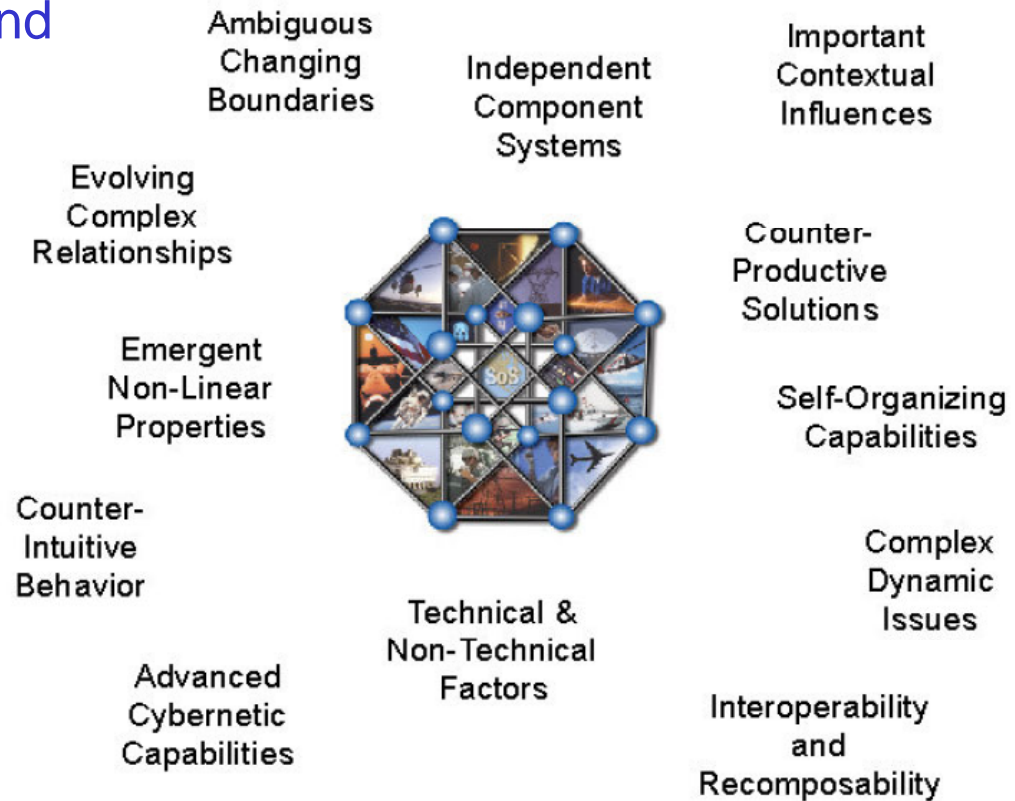
Dr. William J. Reckmeyer, Plenary Address, 1st Annual SoS Engineering Conference, 13 June 2005



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# System Characteristics

Each system/subsystems and component is more complex, intelligent, software-controlled, Internetworked with quickening release



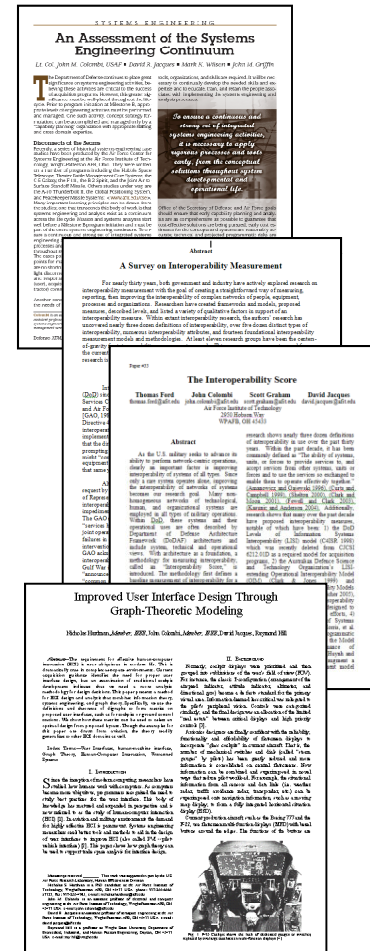
Dr. William J. Reckmeyer, Plenary Address, 1st Annual SoS Engineering Conference, 13 June 2005



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# AFIT Research Thrusts

- **Early application of SE**
  - SoS architecture analysis and evaluation
  - DoDAF support for decision making
  - Interoperability measurement
- **Human System Integration**
  - Allocation of human functions in conceptual design
  - Human centered design
  - Trust in automation
- **Applied design for mission effectiveness**
  - Multi-UAS concepts
  - Theater ISR
  - Integrated Health Monitoring





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# ***AFIT Students ...***

***...mature, motivated, and experienced!***

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- **AFIT students are typically DoD employees**
    - **Most are commissioned officers**
    - **Almost all hold SECRET level clearance or above**
  - **AFIT students have experience in acquiring, testing, sustaining or operating DoD systems**
    - **Almost all of our students have at least 1-2 military assignments under their belt**
    - **They often have direct knowledge of sponsoring organization**
  - **AFIT students understand the importance of their research**
    - **Their lives (or their friend's lives) depend on DoD weapon systems**
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# Sample of Methods/ Tools

## ■ Operational Research

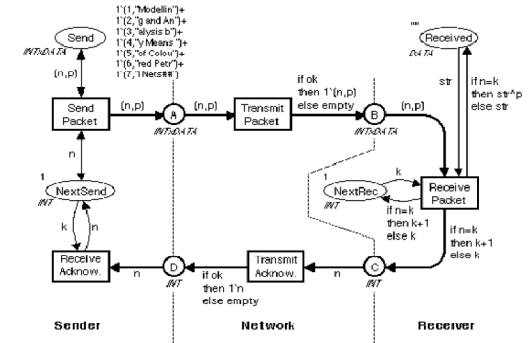
- Discrete event or Agent based simulations
- Monte Carlo analysis, sensitivity analysis
- Optimization methods

## ■ Graph Theory

- PetriNets/ Coloured PetriNets (bipartite directed multigraphs)
  - Many extensions: Stochastic, Hierarchical, Timed, etc
  - Used in Manufacturing, Communications, Protocol development
  - CPNTools, MATLAB PetriNet toolbox

## ■ Complexity Theory

- Biologically inspired Models
- Local collaboration dynamics, Clustering, Self-Organization





# AIR FORCE CENTER FOR SYSTEMS ENGINEERING

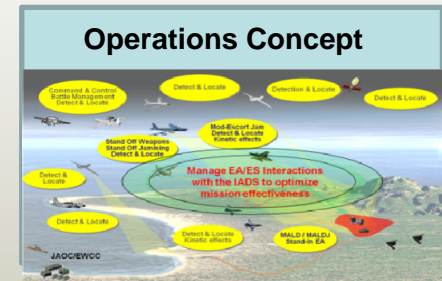
*Creating a Discrete Event Simulation to Determine the Military Worth of Developing an Electronic Warfare Battle Manager Function within an Airborne Electronic Attack System of Systems Architecture*

Research Sponsor: Capability Planning Office ASC/XRS, Wright-Patterson AFB, OH  
Mrs. Trina Bornejko, Maj Charles Glasscock, Maj Dennis Sprengle



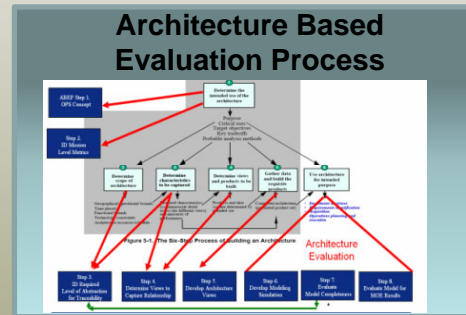
## Problem Statement

How can the AEA SoS architecture be used to evaluate the military worth of an Electronic Warfare Battle Management (EWBM)?

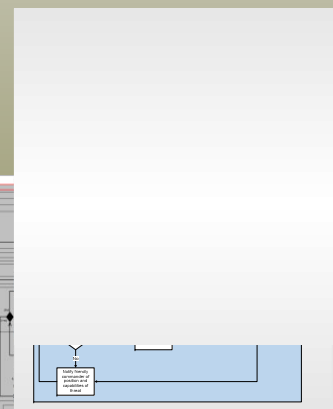


MEASURES of EFFECTIVENESS	NO EWBM	EWBM		
		No Decision Authority	Partial Decision Authority	Full Decision Authority
M1 Minutes to reassign AEA Assets	Baseline	Green	Green	Green
M2 Percent reduction in of SAM detection rate due to Jamming		Green	Green	Green
M3 Percent of strike aircraft Pd by Pop-up SAMs on route		Green	Green	Green
M4 Percent of strike aircraft Pd by known SAMs on route		Yellow	Green	Green
M5 Percent of strike package attritions due to enemy air defenses		Green	Green	Green
M6 Percent of strike packages whose mission is degraded by enemy air defenses		Yellow	Yellow	Yellow

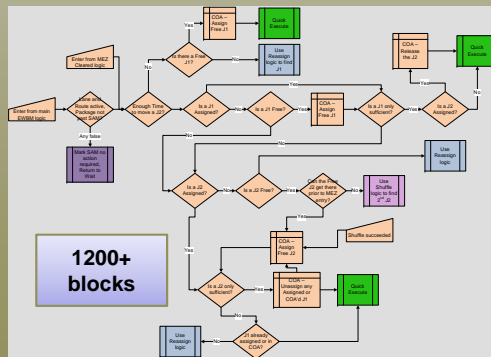
● Statistically significant improvement at 99% C.I.  
● No statistically significant improvement or degradation at 99% C.I.  
● Statistically significant degradation at 99% C.I.



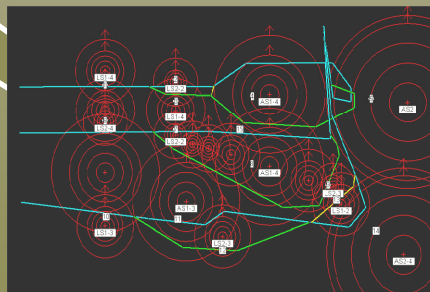
## AEA SoS Architecture



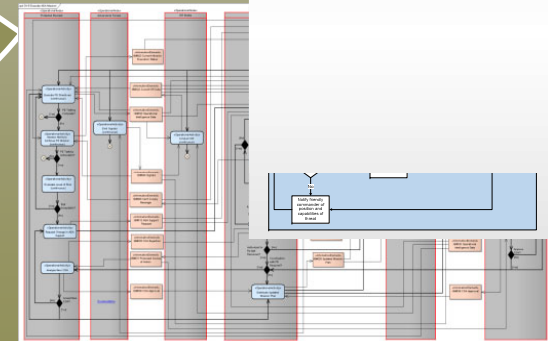
## ARENA Simulation



## Falcon View Mission Plan



## OV-5





**Air Force Institute of Technology**  
**Department of Systems and Engineering Management**  
**INTEROPERABILITY MEASUREMENT AND APPLICATION**  
**Sponsor: Air Force Research Laboratory (AFRL)/Layered Sensing**

**Problem/ Opportunity**

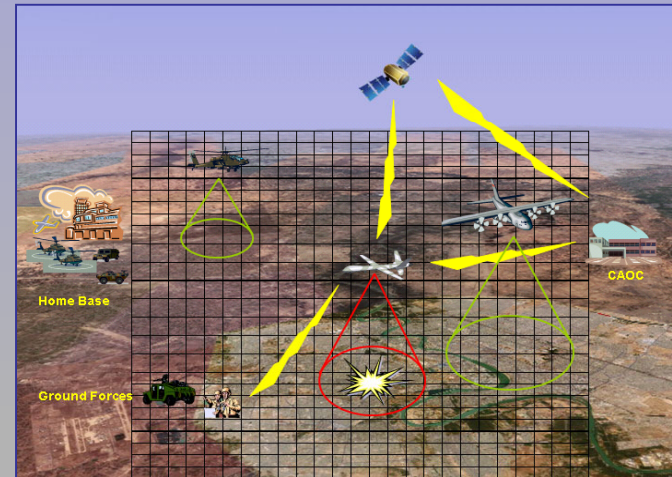
A general method of measuring collaborative and confrontational interoperability does not exist

There is no analytical means of relating the interoperability of a heterogeneous set of systems implementing an operational process to a measure of effectiveness for the process

Classes of Systems	
•Technical	Organizational
Biological	Environmental
Conceptual	Physical
Philosophical	Virtual
Etc...	

*Phylogenetics*

$$S = \{s_1, s_2, \dots, s_n\}$$



**DEFINITION (System Instantiation)**  
 Given a specific  $s \in S$  and a set  $x \subseteq X$  of system characters descriptive of  $s$ , then  $\sigma = x(s)$  is a sequence of system character states, called the instantiation of  $s$ , which models  $s$ .

**Method Application**

- Simulate layered sensing architecture observing urban operations mission thread scenario to obtain Measures of Effectiveness (MOE)
- Link interoperability measurements to MOE

**Interoperability measurement becomes a similarity measure... using systems characters**

$$Sim(\sigma', \sigma'') = wf(\sigma' \cap \sigma'') - \alpha f(\sigma' - \sigma'') - \beta f(\sigma'' - \sigma')$$

$$I = Sim_{Bin}(\sigma', \sigma'') = \left(\frac{1}{n}\right) \sum_{i=1}^n (\sigma'(i) \wedge \sigma''(i))$$

$$I = Sim_{Real}(\sigma', \sigma'') = \left[ \frac{\sum_{i=1}^n \sigma'(i) + \sum_{i=1}^n \sigma''(i)}{2nc_{max}} \right] \left[ 1 - \left(\frac{1}{\sqrt{n}}\right) \left( \sum_{i=1}^n b_i \left( \frac{\sigma'(i) - \sigma''(i)}{c_{max}} \right)^r \right)^{1/r} \right]$$

**INTEROPERABILITY:** The ability of systems, units, or forces to provide services to and accept services from other systems, units, or forces and to use the services so exchanged to enable them to operate effectively together.

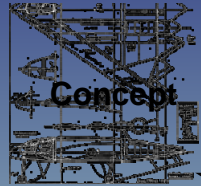




# AIR FORCE CENTER FOR SYSTEMS ENGINEERING

## Long Range Strike 2035: An Analysis of Functional Autonomy

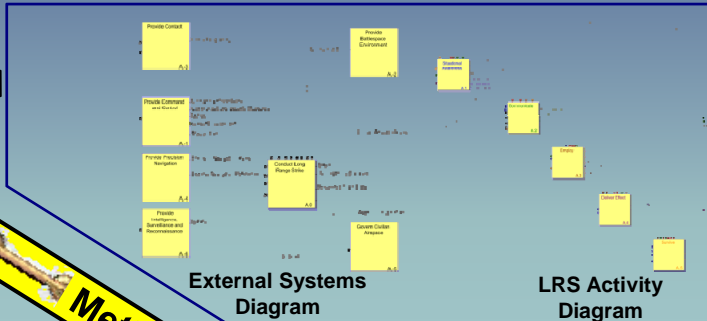
Sponsored by AFRL/RBAA  
 LCDR Scott Rivera      Captain Anil Hariharan      Captain Alan Louie



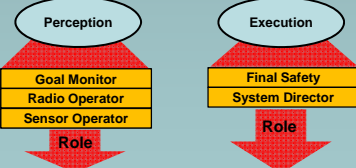
### Establish 2035 Vision



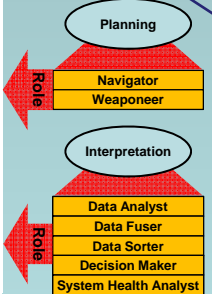
### Describe System



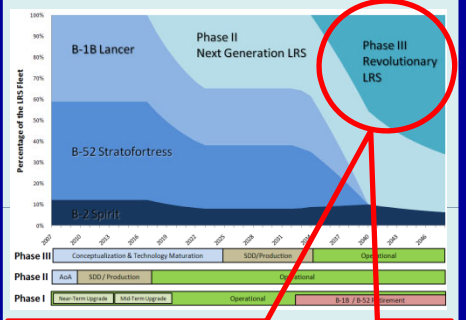
### Identify Human Roles



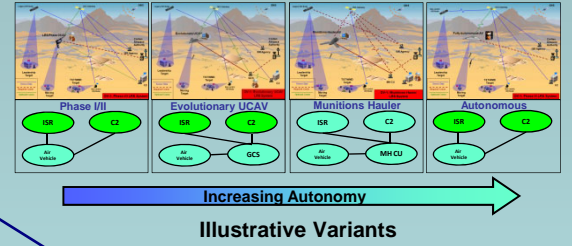
Sub-System	System Function	High Level Activity														
		Situational Awareness	Communicate	Deliver Effect	Employ	Survive	Low Level Activity									
Airframe	Provide Flight Capability	N1.1 Sense Environment	N2.1 Receive Information	N3.1 Engage Target	N4.1 Manage Mission	N5.1 Avoid Engagement	N6.1 Survive Degradation	N7.1 Mitigate Risk								
Propulsion	Provide Thrust	N1.2 Identify Contact	N2.2 Interpret Information	N3.2 Engage Solution	N4.2 Manage Mission	N5.2 Avoid Engagement	N6.2 Survive Degradation	N7.2 Mitigate Risk								
Communication	Provide Interface to GCS	N1.3 Determine Contact Position	N2.3 Interpret Information	N3.3 Engage Solution	N4.3 Manage Mission	N5.3 Avoid Engagement	N6.3 Survive Degradation	N7.3 Mitigate Risk								
Navigation	Provide Navigation	N1.4 Determine Mission Status	N2.4 Interpret Information	N3.4 Engage Solution	N4.4 Manage Mission	N5.4 Avoid Engagement	N6.4 Survive Degradation	N7.4 Mitigate Risk								
Command and Control	Provide Guidance	N1.5 Determine Mission Status	N2.5 Interpret Information	N3.5 Engage Solution	N4.5 Manage Mission	N5.5 Avoid Engagement	N6.5 Survive Degradation	N7.5 Mitigate Risk								
Subsystem	Provide System Status/Health	N1.6 Determine Mission Status	N2.6 Interpret Information	N3.6 Engage Solution	N4.6 Manage Mission	N5.6 Avoid Engagement	N6.6 Survive Degradation	N7.6 Mitigate Risk								
Fire Control	Sense to Firespace Environment	N1.7 Determine Mission Status	N2.7 Interpret Information	N3.7 Engage Solution	N4.7 Manage Mission	N5.7 Avoid Engagement	N6.7 Survive Degradation	N7.7 Mitigate Risk								
Survivability	Mitigate Susceptibility	N1.8 Determine Mission Status	N2.8 Interpret Information	N3.8 Engage Solution	N4.8 Manage Mission	N5.8 Avoid Engagement	N6.8 Survive Degradation	N7.8 Mitigate Risk								
Autonatic Flight Control	Follow Unarmed Flight Profile	N1.9 Determine Mission Status	N2.9 Interpret Information	N3.9 Engage Solution	N4.9 Manage Mission	N5.9 Avoid Engagement	N6.9 Survive Degradation	N7.9 Mitigate Risk								
Weapons Delivery	Provide Effects Delivery Mechanisms	N1.10 Determine Mission Status	N2.10 Interpret Information	N3.10 Engage Solution	N4.10 Manage Mission	N5.10 Avoid Engagement	N6.10 Survive Degradation	N7.10 Mitigate Risk								
Crew Station	React to Human Operator	N1.11 Determine Mission Status	N2.11 Interpret Information	N3.11 Engage Solution	N4.11 Manage Mission	N5.11 Avoid Engagement	N6.11 Survive Degradation	N7.11 Mitigate Risk								
	Protect Human Operators	N1.12 Determine Mission Status	N2.12 Interpret Information	N3.12 Engage Solution	N4.12 Manage Mission	N5.12 Avoid Engagement	N6.12 Survive Degradation	N7.12 Mitigate Risk								



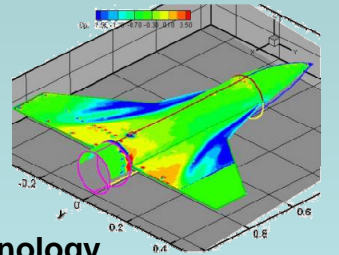
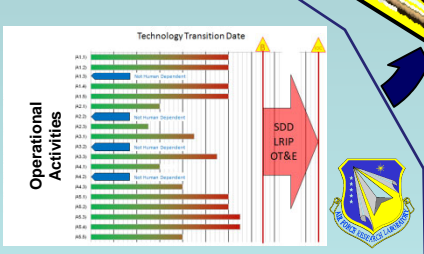
### Problem



Can the 2035 LRS System be Automated?



### Forecast Technology



### Results

- The 2035 LRS system can be Automated
- Concept can be linked to enabling Technologies



**EMPIRICAL METHODS FOR HUMAN SYSTEMS INTEGRATION**  
 Research Sponsor: 711th Human Performance Wing (711th HPW/RH)

**Problem/ Opportunity:**

Many projects and systems still fall short of effectively integrating humans in the systems engineering processes. Improve quantitative methodology to integrate human considerations into early system design

**Method Summary**

- Improves display layout design and evaluation by transforming the problem into graph-theoretic models and performing subsequent analysis

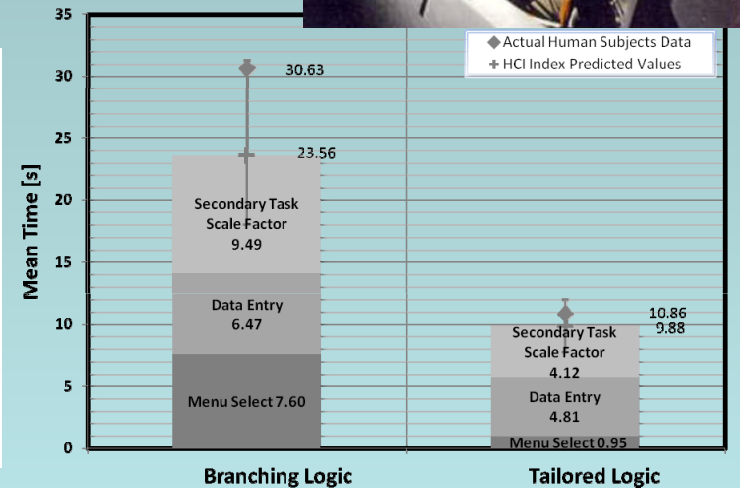
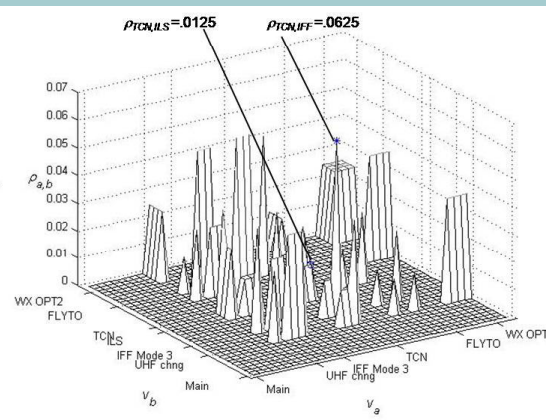
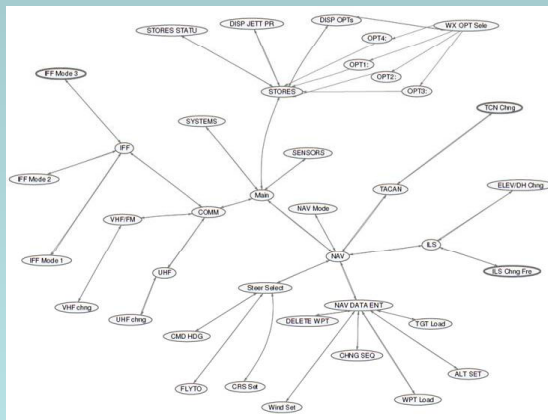


**Time to move through a submenu**

$$d_w(v_0, v_k) = \sum_{i=1}^k \left( t_i + \left( 0.212 + (0.152) \log_2 \left( d^+(v_{i-1}) + 1 \right) \right) \right)$$

**Avg control time, HCI Index**  $D_{w,\rho}(G) = \sum_{v_a, v_b \in V(G)} d_w(v_a, v_b) \cdot \rho_{a,b}$

Compared to F-15 and A-7 test data from AFRL cockpit design research, Reising and Curry, 1987





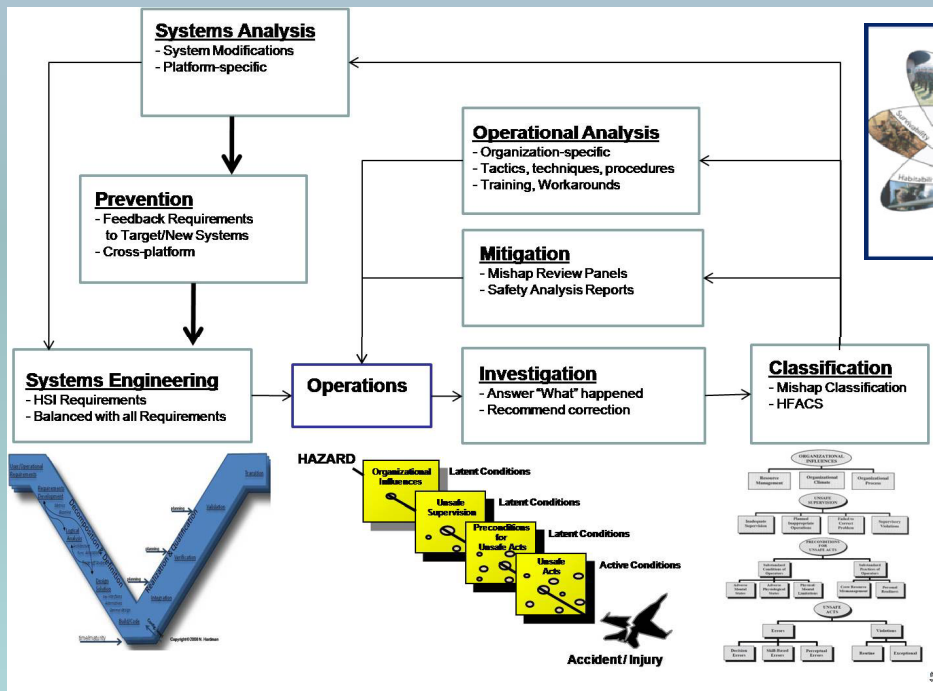
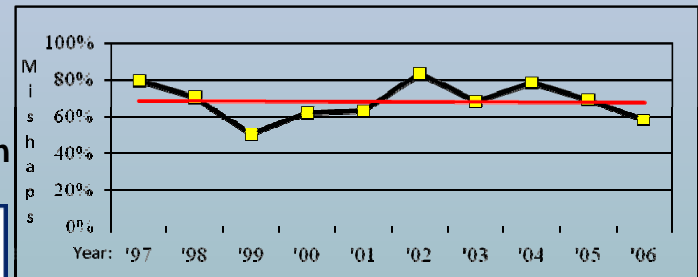
**Air Force Institute of Technology**  
**Department of Systems and Engineering Management**



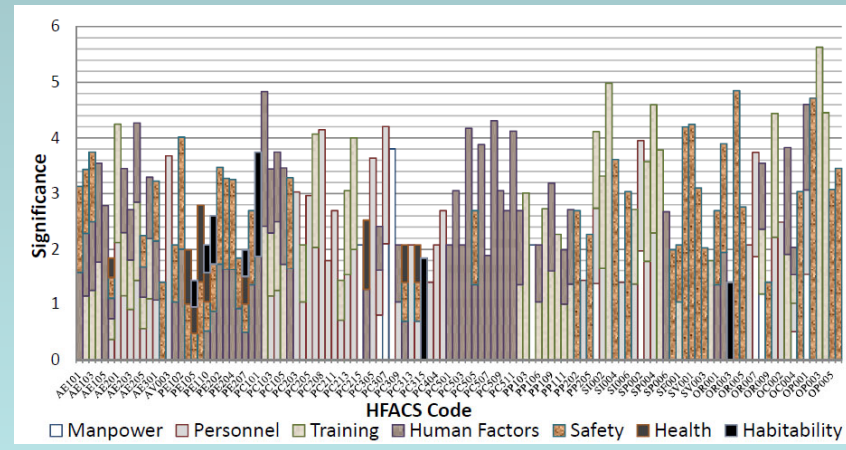
**EMPIRICAL METHODS FOR HUMAN SYSTEMS INTEGRATION**  
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Many projects and systems still fall short of effectively integrating humans in the systems engineering processes. Improve quantitative methodology to integrate human considerations into early system design



HFACS	Description	Related Domain(s)
OP003	Procedural Guidance/Publications	Training
SI003	Local Training Issues/Programs	Training
OR004	Acquisition Polies/Design Processes	Safety
PC102	Channelized Attention	Training, Human Factors
OP002	Program and Policy Risk Assessment	Safety
OP001	Ops Tempo/Workload	Human Factors, Manpower, Personnel
SP004	Limited Total Experience	Training, Personnel
OP004	Organizational Training Issues/Programs	Training



**Method Summary**

- Study mishaps in legacy systems where human error was identified as a causal factor
- Quantify the effect of human-machine interaction
- Use that empirical data to predict, and justify, requirements for new system design



# AIR FORCE CENTER FOR SYSTEMS ENGINEERING

## COOPERATIVE UNMANNED AERIAL SURVEILLANCE CONTROL SYSTEM

Sponsored by AFRL/RV, AFRL/RBC, and AFRL/RW



**LCDR Ted Diamond**  
**Capt Chris Booth**

**Maj Adam Rutherford**  
**Capt Shannon Farrell**

**Maj Brett Taylor**  
**Mr. Austin Smith**

### OVERALL OBJECTIVES

- Develop a CONOPs and conceptual architecture for cooperative UAV control
- Create a test bed for cooperative control research
- Evaluate concurrently developed UAV algorithms

Adaptable Sensor Coverage

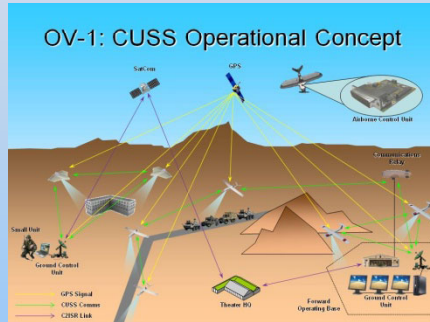
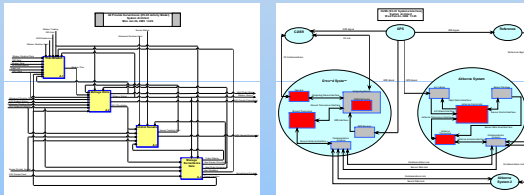
Increased Sensor Coverage

Reduced Revisit Time

Persistent Surveillance

Test Bed

### Conceptual Architecture



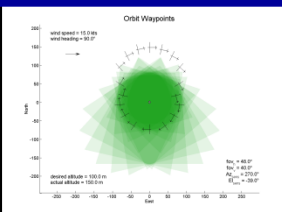
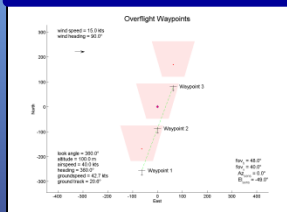
- ### Flight Test Results
- Auto Pilot Tuning
  - Navigation Accuracy
  - UAV Performance
  - Communication Challenges
  - Sensor Feed Constraints
  - Human Factors Considerations

### Control Algorithm Development

### Sensor Aimpoint Flight Plan Algorithms

#### Overflight

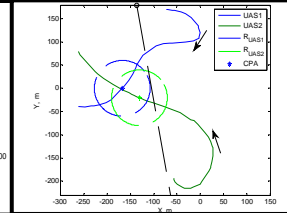
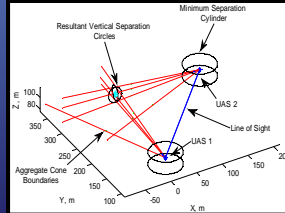
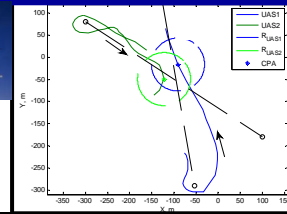
#### Orbit



### UAS Collision Avoidance Algorithm

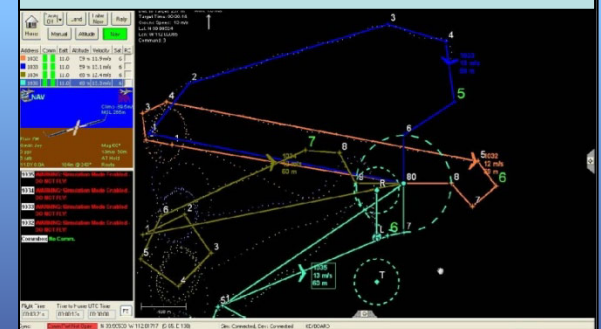
#### Theory and Control

#### Results



### Cooperative Control Algorithm

Coordinated approach and orbit of a fixed target



### OVERALL RESULTS

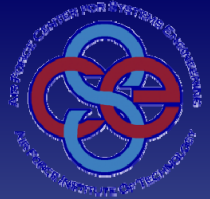
- Created conceptual architecture
- Flew 4 UAVs simultaneously
- Identified UAV cooperative control risks & challenges
- Demonstrated UAV algorithms



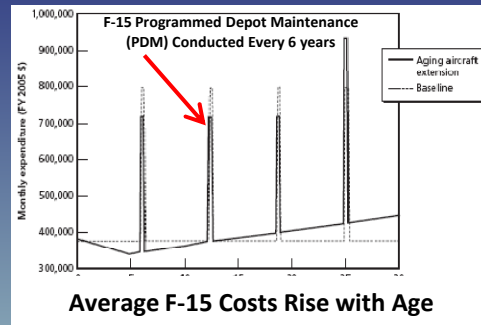
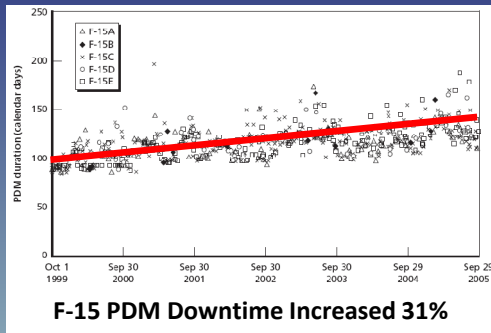
# AIR FORCE CENTER FOR SYSTEMS ENGINEERING

## Integrated Structural Health Monitoring for Aging Aircraft III

Research Sponsor: AFRL/RXLP  
 Captain Jason Brown 1Lt Travis Hanson

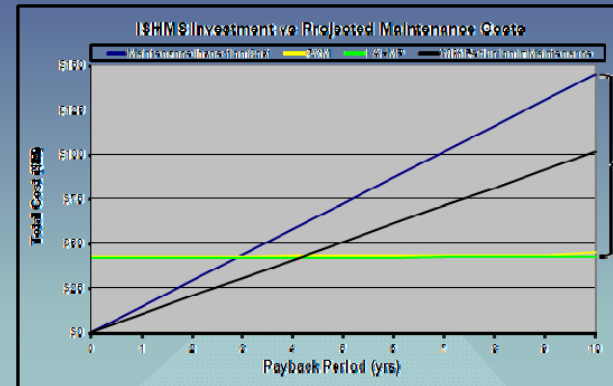


### The Problem



### The Results

Significant Cost Savings Over Current Inspection Methods with Increased Visibility of Structural Deficiencies and Safety of Flight



### Methodology:

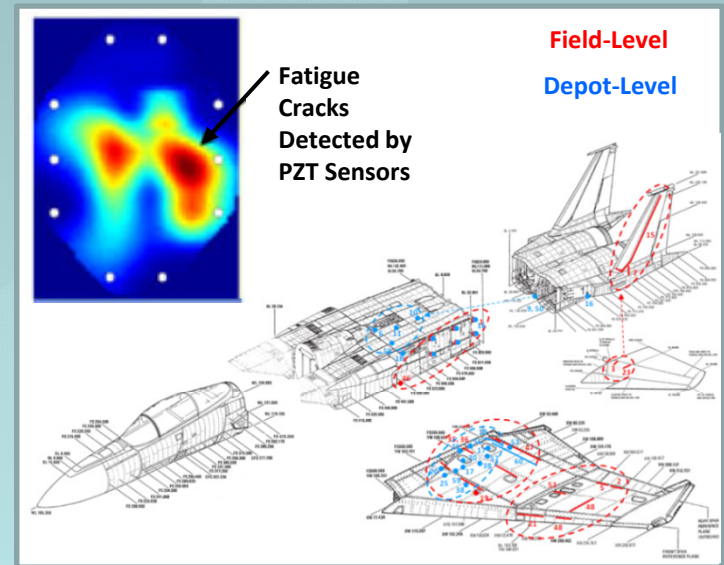
- Used Strategic Guidance → Developed CONOPS
- Functional Area Analysis → Identified Capability Needs
- Functional Needs Analysis → Identified Current Capabilities
- Functional Solution Analysis → Conducted Analysis of Alternative Solutions



### Analysis of Solutions:



Provides Near Real-Time Monitoring of Crack Initiation and Propagation



### Necessary Capabilities:

- Reduce Sustainment
- Maintain Situational Awareness
- Facilitate Informative Decision Making
- Assess Performance and Implementation Improvements

The Large Area Health Monitoring Processor (LAHMP) Family of Miniaturized Prognostic and Health Monitoring (PHM) Systems

**User Connection Options**

- WiFi (802.11 a/b/g)
- USB
- Ethernet
- Bluetooth
- IrDA
- WiMax
- Zigbee
- and more...

**Vehicle Data Bus Connection Options**

- MIL-STD-1553
- DeviseNet
- Ethernet/IP
- ARINC
- Can
- and more...

**Multiple Sensor Types**  
Standard or wireless connections.





**U.S. AIR FORCE**

# *Summary*

- **AFIT SE research program is growing**
  - **Good balance of basic and applied research**
  - **DoD sponsored work supporting acquisition, sustainment and operational communities**
- **AFIT faculty and students provide perspective unmatched in civilian universities**
  - **Students know DoD challenges because they live them**
  - **Military/civilian faculty mix provides balance between new initiatives and sustained research in depth**
- **AFIT research strengths**
  - **Architecture, early application of SE**
  - **Human System Integration**
  - **Applied design for mission effectiveness**