

15<sup>th</sup> INTERNATIONAL CONFERENCE ON INFORMATICS
IN CONTROL, AUTOMATION AND ROBOTICS

PORTO, PORTUGAL

29 - 31 JULY, 2018

REGULAR PAPER SUBMISSION: MARCH 13, 2018



**Conference Areas** 

Intelligent Control Systems and Optimization

**Robotics and Automation** 

Signal Processing, Sensors, Systems Modelling and Control

Industrial Informatics

**Conference Chair** 

Kurosh Madani, University of Paris-EST Créteil (UPEC), France

**Program Chair** 

Oleg Gusikhin, Ford Motor Company, United States

**Keynote Speaker** 

Keith Clark, Imperial College London, United Kingdom

MORE INFORMATION AT: WWW.ICINCO.ORG

# Some of the previous keynote speakers in ICINCO



ALL KEYNOTE LECTURE'S VIDEOS AT: **WWW.ICINCO.ORG/PREVIOUSINVITEDSPEAKERS.ASPX** 

#### Scope

The purpose of the 15th International Conference on Informatics in Control, Automation and Robotics (ICINCO) is to bring together researchers, engineers and practitioners interested in the application of informatics to Control, Automation and Robotics. Four simultaneous tracks will be held, covering Intelligent Control Systems, Optimization, Robotics, Automation, Signal Processing, Sensors, Systems  $Modelling\ and\ Control,\ and\ Industrial\ Informatics.\ Informatics\ applications\ are\ pervasive\ in\ many\ areas$ of Control, Automation and Robotics; This conference intends to emphasize this connection.

#### **Contacts**

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www.icinco.ora



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Membership will be valid until December 31, 2018 No auto-renewal

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# **Satellite Events**



The conference welcomes Satellite Event proposals, and the organizing team is ready to give full support to Workshops, Special Sessions, Tutorials, Demos or Panels that are submitted and get the approval of the advisory board.



SCITEVENTS is organizing this conference

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# **Publication and indexation**



All accepted papers will be published in the conference proceedings, under an ISBN reference, on paper and on CD-ROM support. Moreover, all papers presented at the conference venue will be available at the SCITEPRESS Digital Library.









